

Weak Vector Saddle Point Theorem under Vector ρ, η - Convexity

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Abstract:

In this paper we derive sufficient optimality condition and weak vector saddle point theorem and also duality results for non smooth multiobjective fractional programming problem have been proved.

Key words:

weak vector saddle point, non smooth multiobjective fractional programming, vector ρ - η convexity-invexity for locally Lipschitz theorem.

Introduction:

Xu described saddle point optimality criteria and established duality theorems in terms of generalized Lagrangian functions. Jeya Kumar defined ρ -invexity for non-smooth scalar-valued functions, studied duality theorem for non-smooth optimization problems and gave relationships between Saddle Points & optimality. But no serious attempt is made in utilizing the recent developed concept like Saddle Point Theorem under v - ρ - η -convexity. Hence in this paper an attempt is made to fill the gap by developing vector valued functions under v - ρ - η -convexity which is generalization of the concept of V – convexity and (β, η) convexity and establish sufficient optimality condition and weak vector saddle point theorems and also duality results for non-smooth multiobjective fractional programming problems are obtained.

Definition:

The following are the definitions of Vector v - ρ - η -convexity -invexity for locally Lipschitz functions:

Definition:- Let $\frac{f_i}{g_i} : R^n \rightarrow R$ and $h_j : R^n \rightarrow R$ be locally Lipschitz functions for $i = 1, 2, \dots, p$, and $j = 1, 2, \dots, m$, respectively

(i) $\frac{f_i}{g_i}, i = 1, 2, \dots, p$ is V - ρ - η -convex with respect to functions η and

$\theta : R^n \times R^n \rightarrow R^n$ if there exists $\alpha_i : R^n \times R^n \rightarrow R_+ \setminus \{0\}$ and $\rho_i \in R, i = 1, 2, \dots, p$ such that for any $x, u \in R^n$ and any $\xi_i \in \partial \frac{f_i}{g_i}(u)$,

$$\alpha_i(x, u) \left(\frac{f_i(x)}{g_i(x)} - \frac{f_i(u)}{g_i(u)} \right) \geq \xi_i \eta(x, u) + \rho_i \|\theta(x, u)\|^2.$$

(ii) $h_j, j = 1, 2, \dots, m$ is V - ρ - η -convex with respect to functions η and

$\theta : R^n \times R^n \rightarrow R^n$ if there exist $\beta_j : R^n \times R^n \rightarrow R_+ \setminus \{0\}$ and $\sigma_j \in R, j = 1, 2, \dots, m$

Such that for any $x, u \in R^n$ and any $\phi_j \in dh_j(u)$.

$$\beta_j(x, u) [h_j(x) - h_j(u)] \geq \phi_j \eta(x, u) + \sigma_j \|\theta(x, u)\|^2$$

Let $u \in X$ is said to be a weak minimum of (FP) if there exists no $x \in X$ such that $\frac{f_i(x)}{g_i(x)} < \frac{f_i(u)}{g_i(u)}, i = 1, 2, \dots, p$

Formulation**Primal problem:**

Consider the following non-smooth multi objective fractional programming problems.

$$(FP) : \underset{x \in X}{Min} \underset{1 \leq i \leq p}{Max} \left[\frac{f_i(x)}{g_i(x)} \right],$$

subject to $h_j(x) \leq 0, j = 1, 2, \dots, m$,

where $\frac{f_i}{g_i} : R^n \rightarrow R, i = 1, 2, \dots, p$ and $h_j : R^n \rightarrow R, i = 1, 2, \dots, p$ and $h_j : R^n \rightarrow R, j = 1, 2, \dots, m$ are locally Lipschitz function.

Dual Problem: -

For the problem (FP), consider the dual problem (FD) :

$$(FD) \max \left[\frac{f_i(u)}{g_i(u)} \right]$$

$$\text{subject to } 0 \in \sum_{i=1}^p \tau_i \partial \left[\frac{f_i(u)}{g_i(u)} \right] + \sum_{j=1}^m \lambda_j \partial [h_j(u)]$$

$$\lambda_j h_j(u) \geq 0, j = 1, 2, \dots, m$$

$$\tau_i \geq 0, i = 1, 2, \dots, p$$

$$\lambda_j \geq 0, j = 1, 2, \dots, m,$$

where $e = (1, 1, \dots, 1)^t \in \mathbb{R}^p$

Sufficiency and Duality Theorems:

In this section we show that the generalized karush-kuhn-tucker conditions are sufficient for a weak minimum of (FP)

Theorem: - Let $(u, \tau, \lambda) \in \mathbb{R}^n \times \mathbb{R}^p \times \mathbb{R}^m$ satisfy the generalized karush-kuhn-Tucker conditions as follows.

$$0 \in \sum_{i=1}^p \tau_i \partial \left[\frac{f_i(u)}{g_i(u)} \right] + \sum_{j=1}^m \lambda_j \partial [h_j(u)]$$

$$h_j(u) \leq 0, \lambda_j h_j(u) = 0, j = 1, 2, \dots, m,$$

$$\tau_i \geq 0, i = 1, 2, \dots, p$$

$$\tau^t e > 0$$

$$\lambda_j \geq 0, j = 1, 2, \dots, m$$

If $\frac{f_i}{g_i}$ is V - ρ - η -convex and h_j is v - σ -convex with respect to the same functions η and θ and

$$\sum_{i=1}^p \tau_i p_i + \sum_{j=1}^m \lambda_j \sigma_j \geq 0, \text{ then } u \text{ is weak minimum of (FP).}$$

Proof :- Since $0 \in \sum_{i=1}^p \tau_i \partial \left[\frac{f_i(u)}{g_i(u)} \right] + \sum_{j=1}^m \lambda_j \partial [h_j(u)]$, there exist

$$\xi_i \in \partial \left[\frac{f_i(u)}{g_i(u)} \right] \text{ and } \phi_j \in \partial h_j(u) \text{ such that}$$

$$\sum_{i=1}^p \tau_i \xi_i + \sum_{j=1}^m \lambda_j \phi_j = 0 \quad (4.1)$$

Suppose that u is not a weak minimum of (FP). Then there exists $x \in X$ such that

$$\frac{f_i(x)}{g_i(x)} < \frac{f_i(u)}{g_i(u)}, \quad i=1, 2, \dots, p,$$

since

$\alpha_i(x, u) > 0$ we have

$$\alpha_i(x, u) \frac{f_i(x)}{g_i(x)} < \alpha_i(x, u) \frac{f_i(u)}{g_i(u)}, \quad i=1, 2, \dots, p$$

by the V - ρ - η -convex of $\frac{f_i}{g_i}$, for all i ,

$$\xi_i \eta(x, u) + \rho_i \|\theta(x, u)\|^2 < 0 \text{ for each } \xi_i \in \partial \left[\frac{f_i(u)}{g_i(u)} \right]$$

Hence, we have

$$\sum_{i=1}^p \tau_i \xi_i \eta(x, u) + \sum_{i=1}^p \tau_i \rho_i \|\theta(x, u)\|^2 < 0$$

Since $\sum_{i=1}^p \tau_i \rho_i + \sum_{j=1}^m \lambda_j \sigma_j \geq 0$ it follows from (1)

$$\sum_{j=1}^m \lambda_j \phi_j \eta(x, u) + \sum_{j=1}^m \lambda_j \sigma_j \|\theta(x, u)\|^2 > 0$$

Then, by the v - σ -convexity of h_j , we have

$$\sum_{j=1}^m \beta_j(x, u) [\lambda_j h_j(x) - \lambda_j h_j(u)] > 0$$

since $\lambda_j h_j(u) = 0$, $j = 1, 2, \dots, m$, we have $\sum_{j=1}^m \beta_j(x, u) \lambda_j h_j(x) > 0$ which contradicts the conditions $\beta_j(x, u) > 0$, $\lambda_j \geq 0$ and $h_j(x) \leq 0$.

Thus u is weak minimum of (FP).

Hence the proof.

Weak Duality Theorem:

Let x be a feasible for (FP) and (u, τ, λ) a feasible for (FD), assume that

$\sum_{i=1}^p \tau_i \rho_i + \sum_{j=1}^m \lambda_j \rho_j \geq 0$. If $\frac{f_i}{g_i}$ is V - ρ - η -convex and h_j is v - σ -convex with respect to same functions η and θ , then

$$\frac{f_i(x)}{g_i(x)} < \frac{f_i(u)}{g_i(u)}$$

From feasibility conditions and $\beta_j(x, u) > 0$, we have

$\beta_j(x, u) \lambda_j h_j(x) \leq \beta_j(x, u) \lambda_j h_j(u)$. Then, by the v - σ -convexity of h_j , we have

$$\lambda_j \phi_j \eta(x, u) + \lambda_j \sigma_j \|\theta(x, u)\|^2 \leq 0,$$

for each $\phi_j \in \partial h_j(u)$. Hence we have

$$\sum_{j=1}^m \lambda_j \phi_j \eta(x, u) + \sum_{j=1}^m \lambda_j \sigma_j \|\theta(x, u)\|^2 \leq 0 \text{ for each } \phi_j \in \partial h_j(u).$$

$$\text{Since } 0 \in \sum_{j=1}^p \tau_j \partial \left[\frac{f_j(u)}{g_j(u)} \right] + \sum_{j=1}^m \lambda_j \partial h_j(u),$$

There exists $\xi_i \in \partial \left[\frac{f_i(u)}{g_i(u)} \right]$ and $\phi_j \in \partial h_j(u)$ such that

$$\sum_{i=1}^p \tau_i \xi_i + \sum_{j=1}^m \lambda_j \phi_j \eta(x, u) = 0$$

Hence, from the assumption $\sum_{i=1}^p \tau_i \rho_i + \sum_{j=1}^m \lambda_j \rho_j \geq 0$

We have,

$$\sum_{j=1}^p \lambda_j \xi_j \eta(x, u) + \sum_{i=1}^p \tau_i \rho_i \|\theta(x, u)\|^2 \geq 0$$

from the V - ρ - η -convex of $\frac{f_i}{g_i}$, we have

$$\sum_{i=1}^p \alpha_i(x, u) \left[\tau_i \frac{f_i(x)}{g_i(x)} - \tau_i \frac{f_i(u)}{g_i(u)} \right] \geq 0$$

Since $\alpha_i(x, u) > 0$, $\tau_i \geq 0$, $\tau^+ e = 1$ we have

$$\frac{f_i(x)}{g_i(x)} \preceq \frac{f_i(u)}{g_i(u)}$$

Strong Duality Theorem:

Let \bar{x} be a weak minimum of (FP) at which constraint qualification is satisfied then there exists $\bar{\tau} \in \mathbb{R}^p$ and $\bar{\lambda} \in \mathbb{R}^m \Rightarrow (\bar{x}, \bar{\tau}, \bar{\lambda})$ is feasible for (FD).

If $\frac{f_i}{g_i}$ is V - ρ - η -convex and h_j is v - σ -convex with respect to same function η and θ , then $(\bar{x}, \bar{\tau}, \bar{\lambda})$ is a weak maximum of (FD)

Proof :-

Since \bar{x} is weak minimum of (FP) and a constraint qualification is satisfied \bar{x} , from the generalized Karush-Kuhn-Tucker theorem there exist

$\tau_i \in \mathbb{R}^p$ and $\lambda_j \in \mathbb{R}^m$ such that

$$0 \in \sum_{i=1}^p \tau_i \partial \left[\frac{f_i(x)}{g_i(x)} \right] + \sum_{j=1}^m \lambda_j \partial h_j(\bar{x})$$

$$\lambda_j h_j(\bar{x}) = 0, j = 1, 2, \dots, m$$

$$\tau_i \geq 0, i = 1, 2, \dots, p$$

$$\tau^+ e > 0$$

$$\lambda_j \geq 0, j = 1, 2, \dots, m$$

Since $\tau_i \geq 0, i = 1, 2, \dots, p$ and $\tau^t e > 0$,

we can consider that $\bar{\tau}_i$ and $\bar{\tau}_j$ as

$$\bar{\tau}_i = \frac{\tau_i}{\sum_{i=1}^p \tau_i}, \bar{\lambda}_j = \frac{\lambda_j}{\sum_{j=1}^m \lambda_j}$$

Then $(\bar{x}, \bar{\tau}, \bar{\lambda})$ is feasible for (FD).

Since \bar{x} is feasible for (FP), it follows from weak duality that $\frac{f_i(\bar{x})}{g_i(\bar{x})} <$

$$\frac{f_i(\bar{u})}{g_i(\bar{u})} \quad |$$

for any feasible u for (FD). Hence $(\bar{x}, \bar{\tau}, \bar{\lambda})$ is a weak maximum of (FD).

Weak Vector Saddle – Point Theorem :

In this section, we prove Weak Vector Saddle Point theorem for the non smooth multiobjective fractional program (FP) in which functions are locally lipschitz. For the problem (FP), a point (x, τ, λ) is said to be a critical point if, x is a feasible point for (FP), and

$$0 \in \partial \left[\sum_{i=1}^p \tau_i \partial \left[\frac{f_i(x)}{g_i(x)} \right] + \sum_{j=1}^m \lambda_j h_j(x) \right]$$

$$\lambda_j h_j(x) = 0, \lambda_j \geq 0, j = 1, 2, \dots, m$$

$$\tau_i \geq 0, i = 1, 2, \dots, p,$$

$$\tau^t e = 1$$

Note, that

$$\partial \left[\sum_{i=1}^p \tau_i \frac{f_i(x)}{g_i(x)} + \sum_{j=1}^m \lambda_j h_j(x) \right] = \sum_{i=1}^p \tau_i \partial \left\{ \left[\frac{f_i(x)}{g_i(x)} \right] + \sum_{j=1}^m \lambda_j h_j(x) \right\}$$

$$\text{Let } L(x, \lambda) = \frac{f_i(x)}{g_i(x)} + \lambda_j h_j(x) e,$$

Where $x \in R^m$ and $\lambda \in R^m_+$. Then, a point $(\bar{x}, \bar{\lambda}) \in R^n \times R^m_+$ is said to be a weak vector Saddle Point if when ever we introduce $L(x, \lambda, \mu)$ it means that $L(x, \lambda, \mu)$ has $p -$ components like $\left(\frac{f_i(x)}{g_i(x)} - \lambda_j h_j(x) \right) + \mu^t h_j(x) e$, $i = 1, 2, \dots, p$, $j = 1, 2, \dots, m$

$$L(\bar{x}, \lambda) \not\leq L(\bar{x}, \bar{\lambda}) > L(x, \bar{\lambda})$$

for all $x \in R^n$ and $\lambda \in R^m_+$

Theorem Saddle Point Condition:- Let $(\bar{x}, \bar{\tau}, \bar{\lambda})$ be a critical point of (FP) assume that $\frac{f_i(\bar{x})}{g_i(\bar{x})} + \bar{\lambda}^t h_j(\bar{x}) e$ is $V-\rho-\eta$ -convex with respect to function η and θ and $\sum_{i=1}^p \bar{\tau}_i \rho_i \geq 0$.

Then $(\bar{x}, \bar{\lambda})$ is a weak vector Saddle Point of (FP).

Proof :- Since $(\bar{x}, \bar{\tau}, \bar{\lambda})$ is a critical point for (FP), there exists

$$\xi_i \in \partial \left[\sum_{i=1}^p \frac{f_i(\bar{x})}{g_i(\bar{x})} + \sum_{j=1}^m \bar{\lambda}_j g_j(\bar{x}) \right]$$

such that

$$\sum_{i=1}^p \bar{\tau}_i \xi_i = 0 \quad \text{since} \quad \sum_{i=1}^p \bar{\tau}_i \rho_i \geq 0$$

$$\sum_{i=1}^p \bar{\tau}_i \xi_i \eta(x, \bar{x}) + \sum_{i=1}^p \bar{\tau}_i \rho_i \|\theta(x, \bar{x})\|^2 \geq 0$$

Then, by the $V-\rho$ -invexity of $\frac{f_i(\bar{x})}{g_i(\bar{x})} + \bar{\lambda}^t h_j(\bar{x}) e$,

we have $\sum_{i=1}^p \alpha_i(x, \bar{x}) \bar{\tau}_i \left[\frac{f_i(x)}{g_i(x)} - \frac{f_i(\bar{x})}{g_i(\bar{x})} \right] + [\bar{\lambda}_j h_j(x) - \bar{\lambda}_j h_j(\bar{x})] \geq 0$ for any $x \in R^n$. Since $\alpha_i(x, \bar{x}) > 0$, $\bar{\tau}_i \geq 0$ and $\bar{\tau}^t e = 1$

$$\frac{f_i(\bar{x})}{g_i(\bar{x})} + \bar{\lambda}_j h_j(\bar{x}) e > \frac{f_i(x)}{g_i(x)} + \bar{\lambda}_j h_j(x) e \quad (2)$$

for any $x \in R^n$, that is $L(\bar{x}, \bar{\lambda}) > L(x, \bar{\lambda})$, for any $x \in R^n$.

Now, since $\lambda_j h_j(\bar{x}) \leq 0$ for any $\lambda \in R^m_+$.

$$\bar{\lambda}_j h_j(x) - \bar{\lambda}_j h_j(\bar{x}) \geq 0, \text{ for any } \lambda \in R^m_+$$

$$\text{Thus, } \frac{f_i(x)}{g_i(x)} + \bar{\lambda}_j h_j(\bar{x}) e - \left(\frac{f_i(x)}{g_i(x)} + \bar{\lambda}_j h_j(\bar{x}) e \right) \in R^p_+$$

and hence, $L(\bar{x}, \lambda) > L(\bar{x}, \bar{\lambda})$, for any $\lambda \in R^m_+$.

Therefore, $(\bar{x}, \bar{\lambda})$ is a weak vector Saddle Point of (FP).

Theorem :- If there exists $\bar{\lambda} \in R^m_+$ such that $(\bar{x}, \bar{\lambda})$ is a weak Vector Saddle Point, then \bar{x} is a weak minimum of (FP).

Proof :- Assume that $(\bar{x}, \bar{\lambda})$ is a weak Vector Saddle Point from left of 2nd Equation.

$$\frac{f_i(\bar{x})}{g_i(\bar{x})} + \lambda_j h_j(\bar{x}) e \triangleright \frac{f_i(\bar{x})}{g_i(\bar{x})} + \bar{\lambda}_j h_j(\bar{x}) e, \text{ for any } \lambda \in R^m_+.$$

Thus $\lambda_j h_j(\bar{x}) e \triangleright \bar{\lambda}_j h_j(\bar{x}) e$ for any $\lambda \in R^m_+$, and hence we have

$$\lambda_j h_j(\bar{x}) \leq \bar{\lambda}_j h_j(\bar{x}), \text{ for any } \lambda \in R^m_+ \quad (3)$$

Since λ_j can be taken arbitrary large, $h_j(\bar{x}) \leq 0$. Hence $\lambda_j h_j(\bar{x}) \leq 0$.

Let $\lambda_j = 0$ in (3), $\bar{\lambda}_j h_j(\bar{x}) \geq 0$. Therefore, $\lambda_j h_j(\bar{x}) = 0$. Now, from the right inequality of (2) equation and $\bar{\lambda}_j h_j(\bar{x}) = 0$, we have for any feasible x for (FP),

$$\frac{f_i(\bar{x})}{g_i(\bar{x})} > \frac{f_i(x)}{g_i(x)}$$

Hence \bar{x} is a weak minimum for (FP).

Hence the proof.

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