Abstract—Tunnel fires are not common but they can cause a great damage to lives and properties if happen. Detecting the presence of a fire inside the lengthy and curved tunnel is a tedious process. Detection using Fiber Bragg Grating (FBG) Sensor technique provides a novel methodology by finding not only the presence but also locating the fire inside the tunnel. FBG Sensors are distributed across the inner sides of the tunnel and they are monitored by the Optical Spectrum Analyser (OSA) or Wavelength Division Multiplexing (WDM/Sensor Interrogator) at the exit. The change in the center wavelength from the original spectrum at the output denotes the temperature change (fire occurrence) inside the tunnel. The FBG provides output with more accuracy and it can withstand very high temperature values.

Keywords— Center wavelength, Fiber Bragg Grating Sensor, Optical Spectrum Analyser, Tunnel Fire, WDM Sensor Interrogator.

I. INTRODUCTION

The project Tunnel Fire Detection comes under Structural Health Monitoring (SHM), which involves the process of collecting the information and analyzing it for evaluating the performance of the structure under monitor. The factors that contribute to tunnel fire are tunnel length and its volume. The major tunnel fire accidents are due to ventilation problems, collision of two or more vehicles and lack of information about the number of vehicles inside the tunnel. These along with fuel spillage cause the fire to spread throughout the tunnel in a faster way leading to a catastrophic disaster.

The conditions are even more serious when the length of the tunnel is too long or the tunnel has bends. Because the visibility of the tunnel from one end to the other end is less. Hence the fire occurrence at one end cannot be sensed through the other. Hence many more vehicles may enter the tunnel causing a massive accident.

The fire can be detected using a no. of ways like using of temperature sensor inside the tunnel or monitoring the tunnel through camera. All these can sense the fire inside the tunnel but locating them becomes difficult. The temperature sensor like thermistor cannot withstand very high temperature (say 1000˚C). Also, they have the problem of self-heating. The image processing using cameras inside the tunnel may get damaged due to the fire itself. If we could locate the position of fire in an effective way, we may safeguard the public and properties from massive accident.

The process of sensing and locating is efficiently done by the FBG sensor. The gratings in the FBG sensor cause a narrow range of wavelength to shift and the rest of it to transmit through it [3]. The center of the reflected wavelength is the Bragg’s Wavelength. These characteristics of FBG sensor is utilized to measure temperature or strain changes in the structures. They have the greater temperature withstanding capability, more immune to EMI (Electro Magnetic Interferences), longer life time, explosion safe and it can be multiplexed. The FBG sensors are designed and simulated here using OptiGrating and OptiSystem software. Also, the temperature changes inside the tunnel are visualized using COMSOL Multiphysics Software.

II. FBG SENSOR

FBG is short segment of optical fiber that reflects particular wavelength of light and transmits all other wavelengths [6]. It acts as an optical notch filter. The reflection is due to the grating patterns inside the fiber. FBGs are built by using holographic interference or a phase mask to expose small length of fiber to a periodic distribution of light intensity. The wavelength is reflected based on the Bragg’s equation,

\[ \lambda_B = 2 n_{eff} \Lambda \]

(1)

Where \( \lambda_B \) is the Bragg’s wavelength, \( n_{eff} \) is the effective refractive index of the grating inside the core of the fiber, \( \Lambda \) is the grating period. Only the wavelength of light that satisfies this Bragg’s equation gets reflected.

The value of the reflected wavelength changes based on changes in the temperature. When there in an increase in temperature (as in fire conditions), the fiber elongates causing the grating pattern to vary. Hence the effective refractive index of the grating increases leading to change in wavelength shift at the reflected port of the FBG sensor. This indicates the intensity of fire inside the tunnel structure. And when the temperature reaches back to normal, the wavelength shift comes back to its center wavelength. There is no process of hysteresis.
The change in refractive index is induced by the thermo-optic coefficient and the thermal expansion coefficient.

\[ \Delta \lambda_B = \lambda_B (\alpha + \beta) \Delta T \]  

(2)

Where \( \alpha \) is the thermo-optic coefficient of the grating of the fiber and \( \beta \) is the thermal expansion coefficient of the fiber.

\[ \alpha = \frac{1}{n_{\text{eff}}} \frac{\partial n_{\text{eff}}}{\partial T} \]  

(3)

\[ \beta = \frac{1}{\lambda} \frac{\partial \lambda}{\partial T} \]  

(4)

In this paper, the FBG sensor is designed using the OptiGrating software and a setup is made in OptiSystem where 3 of the designed sensors are arranged in a distributed manner across a tunnel of length 4 km [9]. Each sensor is provided with a varying temperature (fire conditions) and is simulated.

III. METHODOLOGY

Here a tunnel like setup is being assumed and 3 FBG sensors are placed in a distance of 1 km apart each other. Initially these FBG sensors are designed for same temperature (25°C). They all are provided with a same center wavelength of 1550 nm. The input is provided to the 3 FBG sensors through 3 light sources simultaneously and the reflected spectrums of the 3 sensors are individually monitored through 3 OSA or WDM Sensor Interrogator as illustrated in Fig.1.

In practical conditions, instead of using 3 separate input sources, single source can be used which can feed all the FBG Sensors.

The output from each sensor will be the same i.e. the reflected spectrum of all the sensors are at the same center wavelength [6].

But during the condition of fire as in Fig.2, the temperature reading at each sensor will be varied, so as their reflected spectrum shifts away from that of the output obtained to the ideal reference value (25°C).

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The designed tunnel structure is then imported into COMSOL Multiphysics Software. Here the FBG sensor is first separately designed using the parameters [10] as shown in Table.1.

<table>
<thead>
<tr>
<th>Name</th>
<th>Expression</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>n1</td>
<td>1.4457</td>
<td>Core Refractive Index</td>
</tr>
<tr>
<td>n2</td>
<td>1.425</td>
<td>Cladding Refractive Index</td>
</tr>
<tr>
<td>n3</td>
<td>1.446</td>
<td>Step index grating Refractive Index</td>
</tr>
<tr>
<td>N</td>
<td>5</td>
<td>No. of periods</td>
</tr>
<tr>
<td>P</td>
<td>536[nm]</td>
<td>Grating period</td>
</tr>
<tr>
<td>L</td>
<td>N*10^4P</td>
<td>Length of the fiber</td>
</tr>
<tr>
<td>n_eff</td>
<td>(n1+n2)/2</td>
<td>Effective Refractive Index</td>
</tr>
<tr>
<td>lambda</td>
<td>2<em>n_eff</em>P</td>
<td>Incident light wavelength</td>
</tr>
<tr>
<td>f_0</td>
<td>c_const/ lambda</td>
<td>Frequency of light</td>
</tr>
<tr>
<td>r_core</td>
<td>10[um]</td>
<td>Core Radius</td>
</tr>
<tr>
<td>r_cladding</td>
<td>62.5[um]</td>
<td>Cladding Radius</td>
</tr>
</tbody>
</table>

Now the designed FBG sensor is placed at 3 different locations in the Tunnel structure. Heat is generated inside the structure using the Heat Transfer Module in COMSOL as shown in Fig. 4. This provides tabulation for temperature at each sensor during different time instants [5]. The values are then plotted to obtain temperature vs. time graph for each of the 3 sensors (Fig.5).

V. SIMULATION

5.1. OptiGrating Section

OptiGrating is specialized software from Optiwave that has a module for designing Fiber Bragg Grating Sensor. The physical parameters like temperature and strain can be modified based on the requirement and its reflected and transmitted spectrum can be analyzed.

Here 3 FBG Sensors with 1550 nm center frequency, 2 nm linear chirp and no apodization are designed. The reflected and transmitted spectrum is obtained for normal condition 25˚C as shown in Fig.6. The temperature is varied for multiple values (up to 1000˚C) and the results are saved in the format that can be exported to OptiSystem Software.
Optical fiber of 1 km is placed between each sensor. The input to the FBG Sensor is provided through the Mach-Zehnder Modulator. The pulse launched to the sensor is Non-Return to Zero. The simulated setup is illustrated as in Fig. 7.

During normal conditions the output at OSA is same from all 3 Sensors. But at fire situation, consider the temperature of Sensor 1 is 600°C, Sensor 2 is 900°C and Sensor 3 is 100°C. The outputs are obtained as shown in Fig.8. (Blue colour denotes Reference Spectrum and Red colour denotes Shifted Spectrum)

5.3. Results

The simulation result as illustrated in Fig.8 shows that a major shift in Bragg’s wavelength is provided by the FBG Sensor 2. The new center wavelength is 1556 nm that is shifted from 1550 nm. Sensor 1 is shifted to 1553.8 nm which is less than the shift provided by the Sensor 2. The Sensor 3 which has the least change in temperature has a new value of 1550.41 nm.

From the output values we would locate the position of the fire in the sensing area. Since the shift is more in Sensor 2, the fire accident must be near the location of the FBG Sensor 2.

Also, the Sensor 1 has a considerable change in the reflected output spectrum than Sensor 3. So, the fire must be between Sensor 1 and Sensor 2 and Sensor 3 must be away from the fire incident.

The temperature is varied for different values in an FBG Sensor and its corresponding change in wavelength pattern is studied. The reference temperature is taken as 25°C. The readings are given in Table.2 and it is plotted for Change in Temperature vs. Change in Wavelength as shown in Fig.9.

<table>
<thead>
<tr>
<th>AT (°C)</th>
<th>ΔλB (nm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>25</td>
<td>0.36</td>
</tr>
<tr>
<td>75</td>
<td>1.0358</td>
</tr>
<tr>
<td>175</td>
<td>2.478</td>
</tr>
<tr>
<td>275</td>
<td>3.898</td>
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<td>375</td>
<td>5.316</td>
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<td>475</td>
<td>6.808</td>
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<tr>
<td>575</td>
<td>8.162</td>
</tr>
<tr>
<td>675</td>
<td>9.618</td>
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<tr>
<td>775</td>
<td>10.996</td>
</tr>
<tr>
<td>875</td>
<td>12.418</td>
</tr>
<tr>
<td>975</td>
<td>13.824</td>
</tr>
</tbody>
</table>

VI. CONCLUSION

The simulation result shows sensitivity value of FBG Sensor as 20 pm/°C. Locating the fire inside the tunnel can be made still more precise when the number of FBG Sensors is increased for the considered tunnel length of 4 km.
This can also help rescuing operations very fast and can safeguard many lives and properties.

The future work requires hardware implementation of the simulation setup and compares both the hardware and software results.

VII. REFERENCES


