

Optimization of Job Shop Scheduling Problems in Cellular Manufacturing Systems

B. Dhakshina Murthy^{1*}, S. Dhineshkumar^{2*},
A. Arulselvan^{3*}, P. Bharathi^{4*}

(1, 2, 3, 4)- UG Scholar,

Department of Mechanical Engineering,
Hindusthan Institute of Technology, Coimbatore-641032,
Tamil Nadu, India.

K. Kalidas^{5*}

5- Associate Professor,

Department of Mechanical Engineering,
Hindusthan Institute of Technology, Coimbatore-641032,
Tamil Nadu, India.

Abstract: Nowadays, there is a strong tendency towards the effectiveness of manufacturing system. Proper scheduling (determining the sequence in which operations are to be performed) of job is indispensable for the successful operation of a shop. Group Technology (GT) has become an increasingly popular concept in manufacturing, which is designed to take advantage of mass production layout and techniques in smaller batch production system. Since the conventional scheduling methods need more computation time an attempt has been made to optimize the scheduling for Cellular Manufacturing System. In this different types of products in the job shop environment are identified and grouping of cells is performed using Rank Order Clustering (ROC) method. In the second part, optimization procedure has been developed for the scheduling problem for processing in the machine cells for exploring the optimum schedule by minimizing the total penalty cost due to the delay in meeting the due date.

Keywords: Scheduling, Group Technology, Cellular Manufacturing, Rank Order Clustering

1. INTRODUCTION

Increased competition and fluctuating market demands have driven many manufacturing firms to consider novel approaches to improve productivity and eliminate waste. In the past two decades, manufacturing industries have undergone a revolution, widely considered as the third industrial revolution. Many innovative concepts have surfaced only a few among them have been successful. The concept of Group Technology (GT) is the exploitation of the similarities among processes and component design in such a way that it increases the utilization of resources, and eliminates/reduces non value added activities, i.e. material handling, scraps, downtime, etc. GT exploits similarities in three different ways:

- (i) by performing like activities together,
- (ii) by standardizing similar tasks and
- (iii) by efficiently storing and retrieving information about recurring problems. GT forms the basis of Cellular Manufacturing Systems (CMS).

Cellular manufacturing is a practice that involves grouping similar machines into cells, simultaneously grouping similar components into groups. The CMS offer a great deal of benefits including reduction in material handling times, setup times, lower work in progress and improved quality and less re-work, higher productivity,

increased job status visibility, improved job satisfaction for operators, centralization of responsibilities, simplified planning and control procedure. Cell formation, cell layout and scheduling of jobs in a cell are three operating decisions that must be made when implementing a cellular manufacturing system (CMS). Cell formation and cell layout of design issues while job scheduling is the production planning and control issue. A cell can generally be classified as a flow line type or a job shop type according to process similarities of parts in a cell.

Flow line cells usually have more simplified product flows due to higher part similarity. The job shop cell is an alternative for providing more flexibility. The fact that a job shop cell has more flexibility and can add to a more diverse range of part sub families accounts for its interest in the arena of the expanding product diversity. However, planning and controlling activities in a job shop cell are more difficult due to its higher operational complexity. As indicated in group scheduling procedures in exploit similar setups that exist among individual parts within a part family. Bottleneck management is quite effective in planning and scheduling the job shop with load imbalance. An improperly scheduled and managed bottleneck is likely to incur a significant loss on the shop floor. Several approaches to grouping machines part families have emerged.

A comprehensive review and discussion on different approaches in machine part families' formation in GT can be found in Offodile et al. In a typical CMS environment, however, there could be some exceptional parts, which need to visit machines in the other cells. This fact limits the applicability of group scheduling approaches. This paper addresses the scheduling manufacturing cells in which parts may need to visit different cells.

One of the most important issues to attain benefits of CMS is effective implementation of its scheduling system. Nevertheless, this area not been widely attempted in literature as compared to the cell information problem. Due to the similarities in the design, shape, function, etc., parts in part family generally visit machine in same sequence with minor differences in setup requirements. Therefore a part family can be divided into several groups so that each group needs similar setup requirements. In other words a group is a sub set of a part family and all parts in the same group needed similar setup requirements.

This problem is addressed as job shop group scheduling or briefly group scheduling in the literature in group scheduling it is assumed that each part family can be processed in one cell by duplicating bottleneck machines or subcontracting exceptional parts. However, subcontracting exceptional parts may not be practical or duplicating bottleneck machines may not be possible in every CMS environment due to production economic, budget and manufacturing space limitation etc. Thus in a typical CMS environment, it is difficult to form independent manufacturing cells and mostly there are some exceptional parts that create inter-cellular moves. These constraints limit the applicability of group scheduling methods in real life. Examines three array-based clustering algorithms, namely rank order clustering (ROC), rank ordering clustering-2 (ROC-2) direct clustering analysis (DCA) for manufacturing cell formation, with a real life example 2 demonstrate the effectiveness of various structure in algorithm and present a simulated annealing (SA) based algorithm has been developed for scheduling of parts with in a cell for the objective of minimization of weighted sum of makespan, flow time and ideal time.

To our knowledge, no previous study span incorporated both cells information in the scheduling of jobs in job shop cells. The study proposes a two stage scheduling procedure in a job shop cell. This paper considers a scheduling problem in which intercellular moves are allowed and parts may visit machines in the other cells. This research proposes a meta-heuristic namely Scatter Search method to solve the problem. The literature shows Scatter Search method to perform better for scheduling problems. In the first part of this work different type of product in the job shop environment are identified and grouping of cells is performed using Rank Order Clustering method. In the second part optimization procedure has been developed for the scheduling problem for processing in the machine cells. For keeping the machine sequence fixed as per the cell layout and change the job sequence optimum penalty cost.

This paper is organized as follows: In section 2, the scheduling problem is described and formulated. Section 3 described the cell formation using Rank Order Clustering technique and penalty cost in this work. The computational results of proposed algorithms are reported in section 6. Section 7 contains conclusion.

Batch manufacturing is estimated to be the most common form of production in the United States, constituting more than 50% of total manufacturing activity. There is a growing need to make hatch manufacturing more efficient and produc-

tive. In addition, there is an increasing trend toward achieving a higher level of integration between the designs and manufacturing functions in a firm.

2. DATA REQUIREMENTS

- n number of jobs.
- m number of machines.
- Process sequence- the order by which the processes are to be performed.
- Processing time for all the products on each machine.
- Batch quantity required for each job.
- Target dates.
- Penalty in Rupees per day per part.

3. DATA COLLECTED

Table 1 Time taken for machining the job

Job Name	Jobs No	Shaper	Lathe	Milling	Boring	Welding	Grinding
		Processing Time in Mins					
Nut	1	0	17	0	0	0	0
Bolt	2	0	20	0	0	0	0
Gear	3	60	19	30	15	0	4
Hexagonal Gear	4	65	18	45	4	0	6
Flange Pipe	5	0	50	35	35	27	25
Screw	6	62	58	15	0	0	0
Lead Screw	7	60	35	20	0	0	0
Universal Coupling	8	60	18	20	10	0	6
Lathe Centre	9	63	30	0	0	0	5
Piston Connecting Rod	10	0	0	17	11	0	7
Sprocket	11	0	0	15	55	0	5
Tie Rod End	12	0	26	28	27	0	7
Gear Pump Flange	13	0	27	15	31	17	5

Table 2 6 Machines and 13 Jobs Scheduling Problem

Job	Process Sequence (Machining time in min.)	Due Date	Batch Quantity	Penalty / day/item (Rs.)
1	2(17)	5	200	1
2	2(20)	5	200	1
3	1(60)-2(19)-3(30)-4(15)-6(4)	10	100	15
4	1(65)-2(18)-3(45)-4(4)-6(6)	10	100	15
5	2(50)-3(35)-4(35)-5(27)-6(25)	12	100	20
6	1(62)-2(58)-3(15)	10	100	15
7	1(60)-2(35)-3(20)	10	100	10
8	1(60)-2(18)-3(20)-4(10)-6(6)	10	100	10
9	1(63)-2(30)-6(5)	8	100	10
10	3(17)-4(11)-6(7)	5	100	5
11	3(15)-4(55)-6(5)	8	100	10
12	2(26)-3(28)-4(27)-6(7)	8	100	10
13	2(27)-3(15)-4(31)-5(17)-6(5)	8	100	10

4. RANK ORDER CLUSTERING TECHNIQUE

It is specifically applicable in production flow analysis. It is an efficient and easy-to-use algorithm for grouping machines into cells. In a starting part-machine incidence matrix that might be compiled to document the part in a machine shop (or other job shop), the occupied locations in the matrix are organized in a seemingly random fashion. Rank order clustering works by reducing the part-machine incidence matrix to a set of diagonalized blocks that represent part families and associated machine groups. Starting with an initial parts of machine incidence matrix. The algorithms consist of the following steps:

4.1 STEPS

1. Each row of the matrix. Read the series of 1's and 0's from left to right as a binary number. Rank the rows in 01 if decreasing value. In case of a tie, rank the rows in the same order as they appear in the current matrix. Numbering from top to bottom, is the current order of rows the same as the rank order determined in the previous step? If yes, go to step 7, if no, go to the following step.

2. Reorder the rows in the part-machine incidence matrix by listing them in decreasing rank order, starting from the top.

3. Each column to be matrix. Read the series of 1's and 0's from top to bottom as a binary number. Rank the columns in order of decreasing value, in case of a tie. Rank the columns in the same order as they appear in the current matrix.

4. Numbering from left to right, is the current order of columns the same as the rank order determined in the previous step? If yes go to step 7. If no go to the following step.

5. Reorder the columns in the part-machine incidence matrix by lining them in decreasing rank order, starting with the left column. Go to step 1.

6. Stop

4.2 CELL FORMULATION

Step 1: For each row of machine part matrix, assign binary weight and calculate the decimal weight.

Step 2: Sort out the rows of the binary matrix decreasing order of the corresponding decimal weight.

Step 3: Repeat the preceding two steps for each column.

Step 4: Repeat the steps so that the position of each element in each row and column does not change.

5. RANK ORDER CLUSTERING STEP 1

Job→ Machine↓	Nut	Bol t	Gear	Hexagonal Gear	Flange Pipe	Screw	Lead Screw	Universal Coupling	Lathe Centre	Piston Connecting Rod	Sprocket	Tie Rod End	Gear Pump Flange	Decimal weight	Rank
Shaper	0	0	1	1	0	1	1	1	1	0	0	0	0	1776	5
Lathe	1	1	1	1	1	1	1	1	1	0	0	1	1	8179	1
Milling	0	0	1	1	1	1	1	1	0	1	1	1	1	2031	2
Boring	0	0	1	1	1	0	0	1	0	1	1	1	1	1839	4
Welding	0	0	0	0	1	0	0	0	0	0	0	0	1	257	6
Grinding	0	0	1	1	1	0	0	1	1	1	1	1	1	1855	3

STEP 2

Job→ Machine↓	Nut	Bol t	Gear	Hexagonal Gear	Flange Pipe	Screw	Lead Screw	Universal Coupling	Lathe Centre	Piston Connecting Rod	Sprocket	Tie Rod End	Gear Pump Flange
Lathe	1	1	1	1	1	1	1	1	1	0	0	1	1
Milling	0	0	1	1	1	1	1	1	0	1	1	1	1
Grinding	0	0	1	1	1	0	0	1	1	1	1	1	1
Boring	0	0	1	1	1	0	0	1	0	1	1	1	1
Shaper	0	0	1	1	0	1	1	1	1	0	0	0	0
Welding	0	0	0	0	1	0	0	0	0	0	0	0	1
Decimal Weight	32	32	62	62	61	50	50	62	42	28	28	60	61
Rank	6	6	1	1	2	4	4	1	5	7	7	3	2

STEP 3

Job→ Machine↓	Gear	Hexagonal Gear	Universal Coupling	Gear Pump Flange	Flange Pipe	Tie Rod End	Screw	Lead Screw	Lathe Centre	Nut	Bol t	Piston Connecting Rod	Sprocket	Decimal Weight	Rank
Lathe	1	1	1	1	1	1	1	1	1	1	1	0	0	8188	1
Milling	1	1	1	1	1	1	1	1	0	0	0	1	1	8163	2
Grinding	1	1	1	1	1	1	0	0	1	0	0	1	1	8083	3
Boring	1	1	1	1	1	1	0	0	0	0	0	1	1	8067	4
Shaper	1	1	1	0	0	0	1	1	1	0	0	0	0	7280	5
Welding	0	0	0	1	1	0	0	0	0	0	0	0	0	768	6

STEP 4

Job→ Machine↓	Gear	Hexagonal Gear	Universal Coupling	Gear Pump Flange	Flange Pipe	Tie Rod End	Screw	Lead Screw	Lathe Centre	Nut	Bolt	Piston Connecting Rod	Sprocket
Lathe	1	1	1	1	1	1	1	1	1	1	1	0	0
Milling	1	1	1	1	1	1	1	1	0	0	0	1	1
Grinding	1	1	1	1	1	1	0	0	1	0	0	1	1
Boring	1	1	1	1	1	1	0	0	0	0	0	1	1
Shaper	1	1	1	0	0	0	1	1	1	0	0	0	0
Welding	0	0	0	1	1	0	0	0	0	0	0	0	0
Decimal Weight	62	62	62	61	61	60	50	50	42	32	32	28	28
Rank	1	1	1	2	2	3	4	4	5	6	6	7	7

CLUSTER 1

Table 4 Cluster 1 based on calculated data

Job→ Machine↓	Gear	Hexagonal Gear	Universal Coupling	Gear Pump Flange	Flange Pipe	Tie Rod End	Screw	Lead Screw	Lathe Centre	Nut	Bolt	Piston Connecting Rod	Sprocket
Lathe	1	1	1	1	1	1	1	1	1	1	1	0	0
Milling	1	1	1	1	1	1	1	1	0	0	0	1	1
Grinding	1	1	1	1	1	1	0	0	1	0	0	1	1
Boring	1	1	1	1	1	1	0	0	0	0	0	1	1
Shaper	1	1	1	0	0	0	1	1	1	0	0	0	0
Welding	0	0	0	1	1	0	0	0	0	0	0	0	0

CLUSTER 2

Table 5 Cluster 2 based on calculated data

Job→ Ma- chine↓	Gear	Hexagonal Gear	Universal Coupling	Gear Pump Flange	Flange Pipe	Tie Rod End	Screw	Lead Screw	Lathe Centre	Nut	Bolt	Piston Connectin g Rod	Sprocket
Lathe	1	1	1	1	1	1	1	1	1	1	1	0	0
Milling	1	1	1	1	1	1	1	1	0	0	0	1	1
Grinding	1	1	1	1	1	1	0	0	1	0	0	1	1
Boring	1	1	1	1	1	1	0	0	0	0	0	1	1
Shaper	1	1	1	0	0	0	1	1	1	0	0	0	0
Welding	0	0	0	1	1	0	0	0	0	0	0	0	0

CELL LAYOUT

Table 6 cell layout based on cluster arrangement

CELL	MACHINES	JOBS
Cell 1	1,5	3,4,5,8,12,13
Cell 2	2,3,4,6	1,2,6,7,9,10,11

6.

MAKE SPAN CALCULATION

Table 7 calculation of make span

Job→ Machine↓	Lathe		Milling		Grinding		Boring		Shaper		Welding		Time to complete the process (min)
	IN	OUT	IN	OUT	IN	OUT	IN	OUT	IN	OUT	IN	OUT	
Gear	0	19	19	49	49	53	53	68	68	128	128	128	128
Hexagonal Gear	0	18	18	63	63	69	69	73	73	138	138	138	138
Universal Coupling	0	18	18	38	38	44	44	54	54	114	114	114	114
Gear Pump Flange	0	27	27	42	42	47	47	78	78	78	78	95	95
Flange Pipe	0	50	50	85	85	110	110	145	145	145	145	172	172
Tie Rod End	0	26	26	54	54	61	61	88	88	88	88	88	88
Screw	0	58	58	73	73	73	73	73	73	135	135	135	135
Lead Screw	0	35	35	55	55	55	55	55	55	115	115	115	115
Lathe Centre	0	30	30	30	30	35	35	35	35	98	98	98	98
Nut	0	17	17	17	17	17	17	17	17	17	17	17	17
Bolt	0	20	20	20	20	20	20	20	20	20	20	20	20
Piston Connecting Rod	0	0	0	17	17	24	24	35	35	35	35	35	35
Sprocket	0	0	0	15	15	20	20	75	75	75	75	75	75

MAKE SPAN CALCULATION

Table 8 processed makes span data

Job→ Machine↓	Lathe		Milling		Grinding		Boring		Shaper		Welding		Time to complete the process (min)
	IN	OUT	IN	OUT	IN	OUT	IN	OUT	IN	OUT	IN	OUT	
Nut	0	17	17	17	17	17	17	17	17	17	17	17	17
Bolt	0	20	20	20	20	20	20	20	20	20	20	20	20
Piston Connecting Rod	0	0	0	17	17	24	24	35	35	35	35	35	35
Sprocket	0	0	0	15	15	20	20	75	75	75	75	75	75
Tie Rod End	0	26	26	54	54	61	61	88	88	88	88	88	88
Gear Pump Flange	0	27	27	42	42	47	47	78	78	78	78	95	95
Lathe Centre	0	30	30	30	30	35	35	35	35	98	98	98	98
Universal Coupling	0	18	18	38	38	44	44	54	54	114	114	114	114
Lead Screw	0	35	35	55	55	55	55	55	55	115	115	115	115
Gear	0	19	19	49	49	53	53	68	68	128	128	128	128
Screw	0	58	58	73	73	73	73	73	73	135	135	135	135
Hexagonal Gear	0	18	18	63	63	69	69	73	73	138	138	138	138
Flange Pipe	0	50	50	85	85	110	110	145	145	145	145	172	172

7. PENALTY COST CALCULATION

The penalty cost for the every sequence is calculated as per the following method.

To make one component (Job No.3), the elapsed time is 128 min.

For 100 components, it takes $100 \times 128 = 12800$ min

For a day working hours (2 shift/day) = $16 \text{ hrs} = 16 \times 60 = 960 \text{ min}$

To make 100 jobs, it will take $12800/960 = 13.3$ days

Due date to complete the job 3 is 10 days.

Delay time is 3.3 days

Penalty in Rs. Per day per part of job no.3 is Rs. 15.

Therefore, Penalty = Rs. 4950.

In similar fashion, the penalty for all the jobs is calculated.

Total penalty for this job sequence $f(x) = \text{Rs. } 38100$.

8. CONCLUSION

The main aim of this project is to explore the potential of Scatter Search for optimization of job shop scheduling problems in cellular manufacturing systems. The inherent weakness of many search procedures is that they often get trapped in a region around some local minima. Their ability to breakout of such entrapments and achieve better, ideally global minima, is based on their capacity to provide a suitable mixture of intensification and diversification. Scatter search also provides unifying principles for joining solutions based on generalized path constructions and by utilizing strategic designs where other approaches resort to randomization. This project has addressed the problem of optimizing the scheduling of cellular manufacturing systems, which consist of different manufacturing cells with the objective of minimizing the penalty cost. The problem has been solved using Scatter Search method. Rank Order Clustering technique is used here for the formation of cells. The optimal sequence for scheduling of machines and jobs are identified and provides better optimization of penalty cost.

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