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# Generalized **y**-Axiom for Advanced Engineering Applications

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## ABSTRACT

In this paper we discuss the properties, characterization of  $\gamma$ - open sets, relations between regular open set,  $\gamma$ - open set and semi open set,  $\gamma$ - adherent,  $\gamma$ -closure of a subset A of a topological space,  $\gamma$ - irresolute function between topological spaces and equivalence relation  $\gamma$ - correspondence on the set of a topologies of a set X. The inter relationship between  $\gamma$ -axiom and various Separation axioms.

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## **1. INTRODUCTION**

A subset A of a topological space  $(X, \tau)$  is said to be  $\gamma$ -open iff there exists a regularly open set R such

that  $R\subseteq A\subseteq cl(R)$ The Paper is organized as follows.In section (2) Properties and characterization of  $\gamma$ -open sets and

relations between regular open sets,  $\gamma$ -opensets and semi open sets.

It is interesting to note that

(1)The complement of a  $\gamma$ -open set is again a  $\gamma$ -open set.

(2)Neither the union nor the intersection of two  $\gamma$ -open sets is  $\gamma$ -open. In Section (3), $\gamma$ -adherant,  $\mu$ -closure of a subset A of a topological space, $\gamma$ -irresolute function between topological space and equivalence relation  $\gamma$ -correspondance on the set

of a topologies of a set X.Section (4) is devoted to the study of  $\gamma$ -axiom due to Sharma[27]. Separation axioms  $\gamma T_0$ ,  $\gamma T_1$  and  $\gamma T_2$ 

which are generalizations of separation axioms  $T_{0\!,}T_1$  and

 $T_2$  respectively are studied. It is interesting to note in a topological space all the three axioms  $\gamma T_0$ ,  $\gamma T_1$  and  $\gamma T_2$  coincide. Therefore these axioms are referred as  $\mu$ -axiom. The interrelationship between  $\mu$ -axiom and various separation axioms semi  $T_2$ , semi  $T_1$ , semi  $T_0$ and

 $\gamma T_0$  are discussed.

# 2.γ-open sets

# **Definition : 2.1**

A subset A of a topological space  $(X, \tau)$  is said to be  $\gamma$ -**open** iff there exist a regularly open set R such that R $\subseteq$ A $\subseteq$ cl(R). **Theorem :2.2**  A subset A of a topological space  $(X, \tau)$  is said to be  $\gamma$ -open iff there exist a regularly closed set F such that  $int(F) \subseteq A \subseteq F$ . **Proof**: Assume A is a  $\gamma$ -open set. Since A is  $\gamma$ -open, there exist a regularly open set R such that  $R \subseteq A \subseteq cl(R)$ .  $R=int(cl(R) \Longrightarrow cl(R) = cl(int(cl(R)))$  $\Rightarrow$ F= cl(int(F)). we getA⊆F Hence  $int(F) \subseteq A \subseteq F$ . Hence there exist a regularly closed set F such that  $int(F) \subseteq A \subseteq F$ Let R=int(F) Consider int(cl(R))=int(cl(int(F)))=int(F)=R, Hence  $R \subseteq A \subseteq cl(R)$ Hence A is  $\gamma$ -open. Theorem :2.3 A necessary and sufficient condition for a set A in a topological space  $(X,\tau)$  is said to be  $\gamma$ -open is,  $int(cl(A)) \subseteq A \subseteq cl(int(A)).$ **Proof**: Assume A is a  $\gamma$ -open set in (X,  $\tau$ ). Since A is  $\gamma$ -open, there exists a regularly open set R such that  $R \subseteq A \subseteq cl(R)$ .  $int(cl(R)) \subseteq int(cl(A))$  $R \subseteq int(cl(A))$  $A \subseteq cl(R) \implies int(cl(A)) \subseteq int(cl(R))=R$ Hence  $int(cl(A)) \subseteq R$ Hence  $int(cl(A)) \subseteq A$  $R \subseteq A, R \subseteq int(A) \Longrightarrow cl(R) \subseteq cl(int(A))$  $A\subseteq cl(R), A\subseteq cl(int(A))$ Hence  $int(cl(A)) \subseteq A \subseteq cl(int(A))$ Conversely assume  $int(cl(A)) \subseteq A \subseteq cl(int(A))$ Let R = int(cl(A))Then  $R = int(cl(A)) \subseteq A \subseteq cl(int(A)) = cl(R)$ . Therefore  $R \subseteq A \subseteq cl(R)$ . Theorem :2.4 A is  $\gamma$ -open in a topological space (X,  $\tau$ ) iff A is semiopen as well as semi closed in  $(X, \tau)$ .

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#### **Proof** :

Assume А is γ-open, we get  $int(cl(A)) \subseteq A \subseteq cl(int(A))$  (by theorem 2..3)  $\Rightarrow$  $int(cl(A)) \subseteq A$  and  $A \subseteq cl(int(A))$ .  $A \subseteq cl(int(A))$ , for R = cl(A), we have  $R \subseteq A \subseteq cl(R)$  $int(cl(A)) \subseteq A$ , R=cl(A),for we have  $int(R) \subseteq A \subseteq cl(A) = R$ Conversely assume A is semi open as well as semi closed.  $R \subseteq A \Longrightarrow cl(R) \subseteq cl(int(A))$ Hence  $A \subseteq cl(R) \subseteq cl(int(A))$  $int(R) \subseteq A \subseteq R$  for some closed set R  $A \subseteq R \Longrightarrow cl(A) \subseteq R$ Then  $int(cl(A))\subseteq int(R)\subseteq A$ Hence  $int(cl(A)) \subseteq A \subseteq cl(int(A))$ Hence by theorem 2.3, we have A is  $\gamma$ -open. Corollary :2.5 A set A in a topological space (X, τ) is  $\gamma$ -open iff A=s-cl-s-int(A) and A=s-int-s-cl(A). **Remark : 2.6** By definition of a  $\gamma$ -open set it follows that every regularly open set is a  $\gamma$ -open set and every  $\gamma$ -open set is semi open set, i.e., R O (X,  $\tau$ )  $\subseteq$  V O(X,  $\tau$ )  $\subseteq$  S O  $\subseteq$  (X,  $\tau$ ) However the converse of the above statements are not true in general as shown by the following examples. Example: 2.7 Let  $X = \{a, b, c\}$  and  $\tau = \{\emptyset, X, \{a\}, \{b\}, \{a, b\}\}$  Then  $\{a,c\}$  is a  $\gamma$ -open set but not regularly open. Example : 2.8 Let  $X = \{a, b, c\}$  &  $\tau = \{\emptyset, X, \{a\}\}$  then the set  $\{a,b\}$  is a semi open which is not  $\gamma$ -open. Theorem :2.9 A γ-open set A is if regularly open  $A\subseteq int(cl(A))$ **Proof**: Assume A is  $\gamma$ -open, there exists a regularly open set 0 such that  $O \subseteq A \subseteq cl(O)$ and  $A\subseteq int(cl(A))$  $int(cl(A)) \subseteq O \subseteq A \Longrightarrow int(cl(A)) \subseteq A$ Hence A is regularly open. Theorem :2.10 A semi open set A is  $\gamma$ -open if  $int(cl(A)) \subseteq A$ **Proof**: Since A is semi open, there exists an open set O such that  $O \subseteq A \subseteq cl(O)$ Hence  $A \subseteq cl(O) \subseteq cl(int(A))$ Hence  $A \subseteq cl(int(A))$ By our assumption,  $int(cl(A)) \subseteq A$ Hence  $int(cl(A)) \subseteq A \subseteq cl(int(A))$ Hence by theorem 2.3, we get A is  $\gamma$ -open. Theorem :2.11 A semi closed set A is yopen if  $A \subseteq cl(int(A))$ **Remark : 2.12** Neither the union nor the intersection of two yopen sets is  $\gamma$ -open. Example : 2.13 Let  $X = \{a, b, c\}$  and  $\tau = \{\emptyset, X, \{a\}, \{b\}, \{a, b\}\}$  then  $\{a,c\}$ and {b,c} are γ-open sets. But  $\{a,c\} \cap \{b,c\} = \{c\}$  is not a  $\gamma$ -open sets. Example: 2.14

Let X={a,b,c} and  $\tau = \{\emptyset, X, \{a\}, \{b\}, \{a,b\}\}$  then  $\{a\}$  and  $\{b\}$  are  $\gamma$ -open sets but {a}U{b}={a,b} is not a  $\gamma$ -open set. Theorem :2.15 The complement of  $\gamma$ -open set is again a  $\gamma$ -open set. **Proof**: Assume A is  $\gamma$ -open, there exists a regularly open set R such that  $R \subseteq A \subseteq cl(R)$ Therefore we have  $X-R \supseteq X-A \supseteq X-cl(R)$ Hence  $int(X-R)\subseteq X-A\subseteq X-R$ R is regularly open, X-R is regularly closed. Hence by Theorem 2.2, and from (1), we have A is γ-open. **Theorem :2.16** If A is a  $\gamma$ -open set then (a) int(cl(A))=int(A) (b) cl(R)=cl(A), where R is a regularly open set such that  $R \subseteq A \subseteq cl(R)$ . Theorem :2.17 If A and R are regularly open sets and S is  $\gamma$ -open such that  $R \subseteq S \subseteq cl(R)$ , then  $A \cap S = \emptyset$ , implies  $A \cap S = \emptyset$ . **Proof** : Assume A and R are regularly open sets and S is  $\gamma$ --open such that  $R \subseteq S \subseteq cl(R)$ Since  $A \cap R = \emptyset$ , therefore  $R \subseteq X$ -A. Hence X-A is closed. Therefore  $R \subseteq X$ -A implies  $cl(R) \subseteq X$ -A  $S \subseteq cl(R)$ , we get  $S \subseteq X$ -A. Hence  $A \cap S = \emptyset$ . Theorem :2.18 Intersection of a  $\gamma$ -open set S and regularly open set U is a  $\gamma$ -open set. **Proof**: Since S is  $\gamma$ -open, there exists a regularly open set R Case(i):  $S \cap U = \emptyset$ Let  $S \cap U = \emptyset$ It is obvious that then  $S \cap U$  is a  $\gamma$ -open set. Case(ii): S∩U≠Ø we get  $R \cap U \neq \emptyset$  (by Theorem 2.17) Since  $R \subseteq S$ , we get  $R \cap U \subseteq S \cap U$ If  $x \in S \cap U$ , then either x belongs to U and R (or) x belongs to U and S-R. Case (a): x belongs to U and R. Then  $x \in U \cap R \subseteq cl(U \cap R)$ Hence  $U \cap R \subseteq S \cap U \subseteq cl(U \cap R)$ Therefore,  $S \cap U$  is a  $\gamma$ -open set. Case (b): x belongs to U and S-R. Then x belongs to U and x is a limit point of R, since  $S \subseteq cl(R)$ . Let N be a  $\gamma$ -neighbourhood of x. Then N  $\cap$  U is a  $\gamma$ -neighbourhood of x and (N  $\cap$  U)  $\cap$  R  $\neq \emptyset$  which implies N $\cap$ (U $\cap$ R)  $\neq \emptyset$ Hence x belongs to  $cl(U \cap R)$ Hence  $R \cap U \subseteq S \cap U \subseteq cl(R \cap U)$ Hence  $S \cap U$  is a  $\gamma$ -open set. **Theorem :2.19** If B is a subset of a topological space (X,  $\tau$ ) such that A  $\subseteq$  B  $\subseteq$  cl(A). Then B is  $\gamma$ open if A is  $\gamma$ -open. Hence the claim. **Definition : 2.20** 

Vol. 1 Issue 5, July - 2012

Let  $(X, \tau)$  be a topological space. Then the set of all regular open set forms a base for a topology  $\tau$ on X called the semi regularization topology of X such that  $\tau^* \subseteq \tau$ . The space  $(X, \tau^*)$  is called the semi regularization space of  $(X, \tau)$ .

**Definition : 2.21** 

A topological space  $(X, \tau)$  is said to be **semi regular** iff  $\tau = \tau^*$ .

Lemma : 2.22

R O (X,)=int V O (X,  $\tau$ ), where int V O (X,  $\tau$ ) denotes the collection of the interior of  $\gamma$ -open sets in a topological space  $(X, \tau)$ .

#### **Proof**:

Let  $(X, \tau)$  be a topological space.

Claim: R O (X,)=int V O (X,  $\tau$ )

Let  $A \in int V O(X, \tau)$ .

Then A=int(B) for  $B \in int V O(X, \tau)$ .

A=int(B)=int(cl(B)) (by theorem 2.1.16(a))

Therefore  $A \in R O(X, \tau)$ 

HenceintVO(X,)  $\subseteq$  RO(X, $\tau$ ) .....(1)

Then  $R \in V O(X_{i})$ , (by Remark 2.1.6)

Therefore 
$$R \in int V O(X, \tau)$$

Hence R O  $(X, \tau) \subseteq$  int V O  $(X, \tau)$ .....(2)

From (1) and (2), we have R O (X,  $\tau$ )=int V O (X, τ)

## **Remark : 2.23**

By Lemma 2.22, we get that the collection of  $\gamma$ -open sets generates a topological space on (X,  $\tau$ ). Theorem :2.24

In a semi regular space  $(X, \tau)$ , int  $VO(X, \tau)$ generates topology  $\tau$  on X.

**Proof**:

Assume  $(X, \tau)$  is a semi-regular space.

To prove int V O (X,  $\tau$ ) generates topology  $\tau$  on X. By Lemma 2.22 collection of int V O (X,  $\tau$ ) forms a base for a topology  $\tau$  on X such that  $\tau \subseteq \tau$ . Since X is semi-regular,  $\tau = \tau^{2}$ 

Hence int V O (X,  $\tau$ ) generates the topology  $\tau$ .

## Theorem :2.25

Let  $A \subseteq Y \subseteq X$ , where Y is a regularly open subspace of a topological space (X,  $\tau$ ). Then A  $\in$ V O (X,  $\tau$ ) implies A  $\in$  V O (Y,  $\tau_{y}$ ).

## **Proof**:

Since A is  $\gamma$ -open in X, there is a regularly open set R in X such that  $R \subseteq A \subseteq cl_x R$ .

Hence  $R \cap Y \subseteq A \cap Y \subseteq (cl_x R) \cap Y$ 

Hence  $A \in V O(Y, \tau_y)$ .

#### Theorem :2.26

If R is a regularly-open subspace of a topological space  $(X, \tau)$  and V a  $\gamma$ -open set in X, then  $R \cap V$  is  $\gamma$ -open in R.

#### **Proof**:

Assume R is a regularly open set in a topological space  $(X, \tau)$  and V is  $\gamma$ -open set in X.

By Theorem 2.18, we get  $R \cap V$  is a  $\gamma$ -open set in Х.

Since R is a regularly open subspace of X, we get  $R \cap V$  is a  $\gamma$ -open set in R

(by theorem 2.18).

Theorem :2.27

Let Y be a subspace of a topological space (X,  $\tau$ ) and A  $\in$  V O (Y,  $\tau_{y}$ ). Then A  $\in$  V O (X,  $\tau$ ) iff Y is γ-open in X. **Proof**: Since  $A \in V O(Y, \tau_y)$ , we get  $A \in V O(X, \tau)$ Hence Y is regularly open. Hence Y is a  $\gamma$ -open in Y. i.e.,  $Y \in V O(Y, \tau_y)$ .  $Y \in V O(X, \tau).$ Hence Y is  $\gamma$ -open in X. Conversely assume Y is  $\gamma$ -open in X. Since A  $\in$  V O (Y,  $\tau_{v}$ ), there exists a regularly open set R in Y such that  $R \subseteq A \subseteq cl_v R$ . Let  $R_1$  be a regularly open set in X such that  $R_1 \cap Y = R$ . Then by Theorem 2.18, R is  $\gamma$ -open in X. Hence  $R_1 \cap Y \subseteq A \subseteq cl_v(R_1 \cap Y) = \{cl_x(R_1 \cap Y)\} \cap Y \subseteq cl_x(R_1 \cap Y)$ implies  $R \subseteq A \subseteq cl_x R$  (since  $R = R_1 \cap Y$ ) By applying Theorem 2.19, we have  $A \in V O (X,$ τ). Hence  $A \in V O(X, \tau)$ . **Definition : 2.28** A subset M of a topological space  $(X, \tau)$  is called a  $\gamma$ -neighbourhood of x $\subseteq$ X if there exists a

 $\gamma$ -open set V in X such that  $X \in V \subseteq M$ 

## Theorem : 2.29

Let Y be a subspace of a X and A be a  $\gamma$ neighbourhood of x in Y. Then A is a  $\gamma$  neighbourhood of x in X iff Y is  $\gamma$ -open in X.

# **3**.γ-irresolute functions

#### **Definition : 3.1**

A function f:X $\subseteq$ Y is said to be  $\gamma$ -irresolute iff for any  $\gamma$ -open set V of Y,  $f^{-1}(V)$  is  $\gamma$ -open in X. Theorem: 3.2

An almost-continuous and almost-open mapping f:  $X \subseteq Y$  is  $\gamma$ -irresolute.

#### Theorem: 3.3

An identity mapping on a topological space (X,  $\tau$ ) is  $\gamma$ -irresolute.

#### **Definition : 3.4**

A point x in a topological space  $(X, \tau)$  is said to be  $\gamma$ -adherent of a subset G of X if every  $\gamma$ -open set containing x has a non empty intersection with G.

#### **Definition : 3.5**

The set of all y-adherent points of a set G is called  $\gamma$ -closure of G or the intersection of all  $\gamma$ open sets containing G is known as y-closure of G and denoted as  $\gamma$ -cl(G).

## Theorem: 3.6

If A is a subset of a topological space  $(X, \tau)$ , then

 $A \subseteq s \text{-cl}(A) \subseteq \gamma \text{-cl}(A) \subseteq \delta \text{-cl}(A).$ 

#### **Proof**:

Since every regularly open set is  $\gamma$ -open and every  $\gamma$ -open set is semi open, the Theorem follows.

#### **Definition : 3.7**

A subset A in (X,  $\tau$ ) is said to be  $\delta_{v}$  - closed if  $A = \gamma - cl(A)$ .

#### Remark : 3.8

Two different topologies  $\tau_1$  and  $\tau_2$  on a set X may have same class of

 $\gamma\text{-open sets}.$  This leads to define the notation of  $\gamma\text{-}$  correspondence.

# **Definition : 3.9**

Two topologies  $\tau_1$  and  $\tau_2$  on a set X are said to be  $\gamma$  –correspondent if V O (X,  $\tau_1$ ) = V O (X,  $\tau_2$ ).

#### Example : 3.10

Let X={a,b,c} and  $\tau_1 = \{\emptyset, \{a\}, \{b,c\}, X\}$  and  $\tau_2 = \{\emptyset, \{a\}, \{c\}, \{a,c\}, \{b,c\}, X\}$ , then V O (X,  $\tau_1$ ) = V O (X,  $\tau_2$ ).

# Theorem : 3.11

The relation of  $\gamma$ -correspondence on the collection of all topologies on a set X is an equivalence relation.

#### 4.γ**-axiom:**

#### **Definition : 4.1**

A topological space  $(X, \tau)$  is said to be  $\gamma T_0$ if for each pair of distinct points x,y of X there exists a  $\gamma$ -open set G containing x but not y (or) a  $\gamma$ -open set T containing y but not x.

#### **Definition : 4.2**

A topological space  $(X, \tau)$  is said to be  $\gamma T_1$ if for each pair of distinct points x,y of X there exists a  $\gamma$ -open set G containing x but not y (or) a  $\gamma$ -open set H containing y but not x.

#### **Definition : 4.3**

A topological space  $(X,\tau)$  is said to be  $\gamma T_2$  if for each pair of distinct points x, y of X there exists a  $\gamma$ -open set G and H such that  $x \in G, \ y \in H$  and  $G \cap H = \emptyset$ 

#### Theorem: 4.4

For a topological space  $(X, \tau)$  the following are equivalent.

- a) X is  $\gamma T_0$
- b) X is  $\gamma T_1$

c) X is  $\gamma T_2$ 

#### **Proof:**

Let  $(X, \tau)$  be topological space. Let x ,  $y \in X$  such that  $x \neq y$ . Since X is  $\gamma$ -T<sub>0</sub>, i.e.,  $x \in G$  and  $y \notin G \Longrightarrow x \notin$ X-G and  $y \in X$ -G Let X-G be H. Then  $y \in H$  also  $G \cap H = \emptyset$ Hence for  $x \neq y \in X$  there exists  $\gamma$ -open set G containing x but not y and a y-open set H containing y but not x. Hence X is  $\gamma T_1$ . Assume X is  $\gamma T_1$ Let x ,  $y \in X$  such that  $x \neq y$ . Since X is  $\gamma T_1$ , there exists a  $\gamma$ -open set G containing x but not y and a  $\gamma$ -open set H containing y but not x. Since  $x \in G$  and  $y \notin G$ , we get  $x \notin X$ -G and  $y \in$ X-G. Let H=X-G. Then H is a  $\gamma$ -open set since G is a open set. Also  $G \cap H = \emptyset$ Hence there exists  $\gamma$ -open sets G and H such that  $x \in G, y \in H \text{ and } G \cap H = \emptyset$ 

## Therefore X is $\gamma T_2$ .

As  $\gamma T_2$  axiom is stronger than  $\gamma T_0$  axiom, the result follows.

## Remark : 4.5

The three axioms  $\gamma T_0$ ,  $\gamma T_1$ ,  $\gamma T_2$  coincide. Hence we shall refer the three axioms as  $\gamma$ -axiom. **Definition : 4.6** 

A topological space  $(X, \tau)$  is said to be  $\gamma$ space if for each pair of distinct points x , y of X there exists a  $\gamma$ -open set G containing x but not y.

# **Proposition : 4.7**

A  $\gamma$ -space X is semi T<sub>2</sub>.

# Proof:

Since every  $\gamma$ -open set is semi open, we have X is semi  $T_2$ .

#### Example: 4.8

Let  $X=\{a,b,c,d\}$ , and  $\tau =\{\emptyset, \{a\}, \{b\}, \{c\}, \{a,b\}, \{a,c\}, \{b,c\}, \{b,d\}, \{a,b,c\}, \{a,b,d\}, \{b,c,d\}, X\}$ . Then X is a semi T<sub>2</sub> space but not a  $\gamma$ -space.

## Remark: 4.10

(i) Since every γ-space is semi T<sub>2</sub> and semi T<sub>2</sub> implies semi T<sub>1</sub>, we get every γ-space is semi T<sub>1</sub>.
(ii) Every semi T<sub>1</sub> space need not be a γ-space.
Example : 4.11

Let X={a,b,c,d}, and  $\tau = \{\emptyset, \{a\}, \{c\}, \{a,c\}, \{c,d\}, \{a,c,d\}, \{b,c,d\},X\}$ . Then the space X is a semi T<sub>1</sub> space which is not a  $\gamma$ -space.

## Example : 4.12

Let X={a,b,c} and  $\tau = \{\emptyset, \{a\}, X\}$ . Then X is a semi T<sub>0</sub> space but not a  $\gamma$ -space.

#### **Proposition :4.13**

Every  $rT_0$  space is a  $\gamma$ -space.

#### Proof:

Let X be a  $rT_0$  space.

Then for each pair of distinct points x, y of X there exists a regularly open set G containing x but not y.

Since every regularly open set is a  $\gamma$ -open set , G is a  $\gamma$ -open set.

Then for each pair of distinct points x , y of X there exists a  $\gamma\text{-open}$  set G containing x but not y.

Hence X is a  $\gamma$ -space.

Hence every  $rT_0$  space is a  $\gamma$ -space.

## Remark: 4.14

The converse of proposition 4.13 is not true.

Example : 4.15 Let X={a,b,c,d}, and  $\tau = \{\emptyset, \{a\}, \{b\}, \{a,b\}, X\}$ . Then X is a  $\gamma$ -space but not rT<sub>0</sub>.

#### **Remark : 4.16**

The concepts of a space being a  $\gamma\mbox{-space}$  and  $T_0\mbox{-space}$  are mutually independent.

#### Example: 4.17

Let  $X=\{a,b,c\}$ , and  $\tau = \{\emptyset,\{a\},\{a,b\}, X\}$ . Then X is a T<sub>0</sub>-space but not a  $\gamma$ -space.

# Example: 4.18

Let  $X=\{a,b,c,d\}, \quad \tau = \{\emptyset, \{a\}, \{b\}, \{a,b\}, X\}.$ Then X is a  $\gamma$ -space but it is not a T<sub>0</sub>-space.

## Remark: 4.19

The axiom of  $\gamma$ -space is independent of the T<sub>1</sub>-axiom.

#### Example : 4.20

Let X be countable set,  $\tau = \{\emptyset, X, A\}$  where A  $\subset$  X such that X-A is finite.

# Example: 4.21

Let  $X=\{a,b,c,d\}$  and  $\tau =\{ \emptyset,\{a\}, \{b\}, \{a,b\},\{d\}, \{a,d\}, \{b,d\}, \{a,b,c\}, \{a,b,d\},X\}$ . Then X is a  $\gamma$ -space but not  $T_1$ .

#### Theorem: 4.22

A space X is a  $\gamma$ -space iff each singleton set in X is  $\delta_{\gamma}$ -closed.

#### **Proof:**

Let X be a γ -space.

Let  $x, y \in X$  such that  $x \neq y$ .

Since X is a  $\gamma$ -space, there exists a  $\gamma$ -open set containing y but not x.

Then  $y \notin \gamma$  -cl{x}.

Hence  $\gamma$  -cl{x}  $\subseteq$  {x}

Therefore  $\{x\} = \gamma - cl\{x\}$ .

Hence  $\{x\}$  is  $\delta_v$ -closed.

 $Conversely \ let \ x \neq y \ \in \ X.$ 

Then by the hypothesis, {x} and {y} are  $\delta_{\rm v}\text{-}$  closed.

i.e.,  $\{x\} = \gamma \operatorname{-cl}\{x\}$  and  $\{y\} = \gamma \operatorname{-cl}\{y\}$ .

Therefore  $y \notin \gamma$  -cl{x} and  $x \notin \gamma$  -cl{y}.

Hence there exists a  $\gamma$ -open set containing x but not y.

Hence X is a  $\gamma$ -space.

## Theorem: 4.23

The necessary and sufficient condition for a space X to be a  $\gamma$ -space is that for each  $x \in X$  there exist a  $\gamma$ -open set U of X containing x such that the subspace U is a  $\gamma$ -space.

#### Theorem : 4.24

Every regularly open subset Y of a  $\gamma\mbox{-space X}$  is a  $\gamma\mbox{-space}.$ 

**Proof:** 

Let Y be regularly open subset of a  $\gamma$ -space X. **Claim:** Y is a  $\gamma$ -space.

Let  $x, y \in X$  such that  $x \neq y$ .

Then  $x \neq y \in X$ .

Since X is a  $\gamma$ -space, there exist a  $\gamma$ -open set G containing x but not y.

Hence  $G \cap Y$  is a  $\gamma$ -open set in Y (by Theorem 2.26), containing x but not Y.

Hence Y is a  $\gamma$ -space.

#### Theorem: 4.25

If f is a  $\gamma$ -irresolute function from a space X to a  $\gamma$ -space Y.Then X is a  $\gamma$ -space.

#### Theorem :4.26

The product of two  $\gamma$ -spaces is a  $\gamma$ -space.

#### CONCLUSION

This paper is an attempt to generalize  $\mu$ -open sets due to Sharma [25] to fuzzyTopological spaces.

 $\mu$ -open sets and  $\mu$ -axiom due to Sharma[25,26] are analyzed.  $\mu$ -open sets, its properties

and characterizations are analyzed.

 $\mu$ -adherent,  $\mu$ -closure of a subset A of a topological space,  $\mu$ -irresolute function between topological

spaces and the relation  $\mu$ -correspondence on the set of the topologies on a set X are analyzed.

separation axioms  $\mu T_{0}$ ,  $\mu T_{1}$  and  $\mu T_{2}$  and their equivalence in topological spaces are discussed. Properties and characterizations of  $\mu$ -spaces are analyzed.

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