

Design of video transform engine by using dct techniques

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ABSTRACT-The technique of spatial and time scheduling strategy is called the space- time scheduling strategy (STS).It achieves high image resolutions in real time systems. The spatial scheduling strategy includes the ability to choose the DA precision bit length. The strategy is a hardware sharing architecture reduces hardware cost arranges different dimensional computations. So it calculates first and second dimensional calculations simultaneously in single 1D-DCT core to reach a hardware utilization of 100%. The hardware sharing architecture utilizes a binary signed digit DA architecture that modifies the arithmetic resources shared during four time slots. The 2D-DCT achieves high accuracy with a small area high throughput rate. While using an 8- bit length; the noise in the image can be reduced to a low level compared to that in a 9-bit length. In addition reduction in area, increased accuracy can be obtained.

key Terms:*Binary Signed Digit (BSD), Discrete Cosine Transform (DCT), Distributed arithmetic (DA)-Based, Space-Time Scheduling (STS).*

I. INTRODUCTION

Discrete cosine transform is a widely applied transform engine for image and video compression applications[1]. The visual media has been built-up towards high-resolution specifications, high definition television (HDTV). Accordingly a high-accuracy and high throughput rate component is used to meet the future applications. In addition to reduce the manufacturing costs of the integrated circuit (IC), a low hardware cost design is also necessitated. Therefore, a high performance video transform engine that victimized high accuracy, a small area, and a high-throughput rate is hoped for VLSI designs. Proposed a novel 8×8 two dimensional (2-D) discrete cosine transform/inverse discrete cosine transform architecture based on the conduct 2-D approach and the rotary motion technique. The computational complexity is reduced by using the special attribute of complex number[3].The 2-D DCT method has been implemented using either direct or indirect method.The direct

methods includes fast algorithm that reduce the computation complexity.It provides a design automation environment with parameter configurations in designing 2-D DCT/IDCT core that is suitable for most image and video compression applications[5].

II. DISTRIBUTED ARITHMATIC

The inner product for a general matrix multiplication and accumulation is given below

$$Y=A^T X=\sum_{i=1}^L A_i X_i \quad (1)$$

Where A_i is a fixed co-efficient and X_i is the input data, and is called the DA co-efficient matrix. DA is an efficient technique for calculation of sum of product or multiplies and accumulates. MAC operation is very common in all digital signal processing applications. It is used in data path circuit designing and area savings. DA implements the MAC using basic building blocks in FPGAS. It is bit-serial and DA is basically a bit-level rearrangement of the multiply and accumulation operation. A smaller area can be achieved by using BSD DA-based architecture.

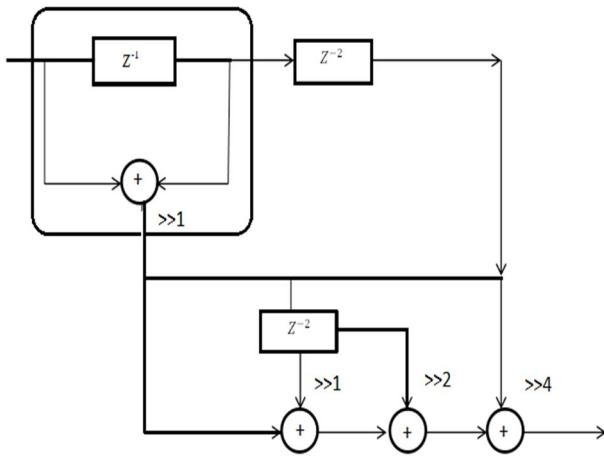


Fig.1. Adder Based DA

A. 2-D DCT core design

The 8x8 2-D DCT is defined as

$$Y_{u,v} = 1/4 K_u K_v \sum_{i=0}^7 \sum_{j=0}^7 x_{i,j} \cos((2i+1)u\pi)/16 \times \cos((2j+1)v\pi/16) \quad (2)$$

Where $K_u = K_v = 1/\sqrt{2}$ for $u=v=0$ and $K_u = K_v = 1$ for $1 \leq u, v \leq 7$.

The 8 point 1D-DCT is defined as

$$Z_n = 1/2 K_n \sum_{m=0}^7 X_m \times \cos((2m+1)n\pi)/16 \quad (3)$$

Where $K_n = 1/\sqrt{2}$ for $n=0$, $K_n = 1$ for $n \neq 0$

By using hardware designs to reduce the computation complexity is row-column disintegration that executes row-wise 1-D transform followed by column-wise transform with arbitrating transposition. The DA-precision bit length for the BSD representation to achieve organization accuracy, share the hardware resource in time to reduce the area cost.

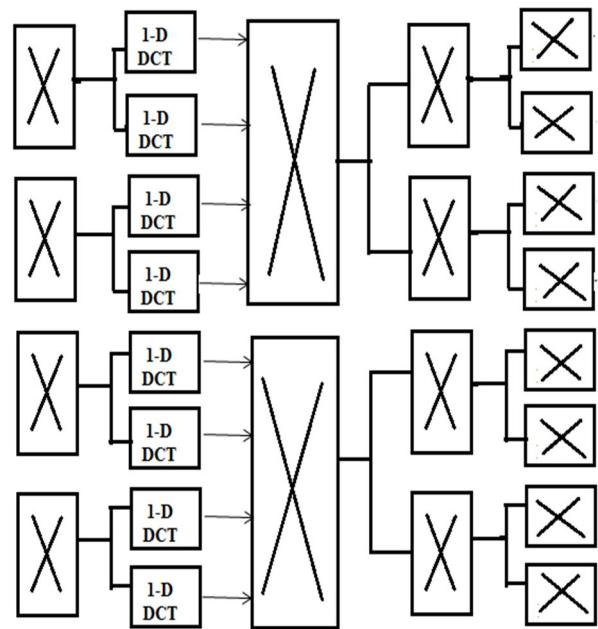


Fig.2. 8x8 2-D DCT

B. Analysis of the co-efficient bits

The co-efficient bits are analyzed by using seven internal coefficient from C1 to C7 for the 2-D DCT transformation. Then it will be expressed as BSD because to save computation time and hardware cost, as well as to achieve the PSNR rate. The PSNR is defined as given below

$$PSNR = 10 \log_{10} 255^2 / MSE_1 \quad (4)$$

The mean-square-error between the original image and the reconstructed image for each pixel. Accuracy between the 8-bit and 9-bit BSD expressions is shown in figure. While the BSD bit length increases the HW also increased. Reduction of the HW cost and improvement in the system accuracy is done by means of 9-bit BSD

Fig 4.system architecture.

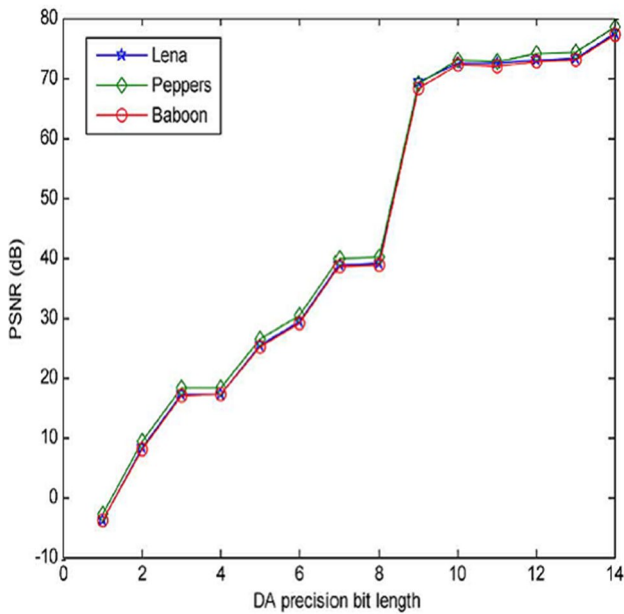
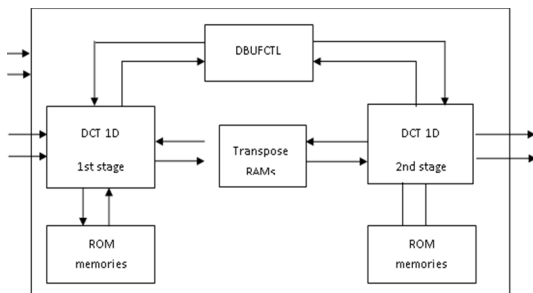


Fig.3.Simulation for system PSNR in different BSD bit length

III. VIDEO TRANSFORM ENGINE

Video Transform Engine core architecture is based two 1D DCT units coupled through transpose matrix RAM. Transposition RAM is double (2 stage) buffered. When 2nd stage of DCT reads out data from transposition memory 1, 1st DCT stage can write 2nd transposition memory with new data. This enables creation of dual stage global pipeline where every stage (both tow stages for each DCT) consists of 1D DCT and transposition memory. 1D DCT units are not internally pipelined; they use a parallel distributed arithmetic with butterfly computation as per digital signal processing for video to compute DCT values. Design based on distributed arithmetic does not use any multipliers for computing MAC (multiply and accumulate), instead it stores precompiled MAC results in ROM memory and grab them as needed. DBUFCTL block is a memory arbiter between 1D DCT stages



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IV. HARDWARE SHARING STRATEGY

The hardware shares the resources in order to reduce area cost by suing some modules. Those modules are modified two-input butterfly module(MBF2),process element even(PEE),process element odd(PEO),pre-reorder and post-reorder.

A. Modified butterfly module

Genrally BF2 has a hardware utilization rate in the adder and subtracter of 50%.Additional multiplexers and reorder registers are added to the proposed MBF2 module in order to enble the hardware resources to be shared.The reorder registers consist of four word registers that use the control signals to select the input data and use enable signals to output data.The operation of the proposed MBF2 has an eight clock cycle period similar to BF2. The pre-reorder module operation of the hardware resources can be shared the hardware resources by reording the inputs during the four separate time slots

B. Process element module

The DA-based computation, even part and odd parttransformation can be implemented using PEE and PEO.Hardware shares the resources at the bit level.The even adder tree(EAT) and odd adder tree(OAT) using the error compensated adder tree.The even part transformation can be extended based on DA computation formats

C. Post-Reorder Module

This is the last stage of the 1-D DCT computation,the data sequence after the PEE and PEO must be merged and repermuted in the post-reorder module.Then the post-reorder module permutes the data order in sequence.Twomultiplexers are selected that is fed into the different reorder registers.

D. 2-D DCT Core Architecture

To save the hardware costs the proposed 2-D DCT core is implemented using a single 1-D DCT and one TMEM. The 1-D DCT core includes an MBF2, a pre-reorder module, a PEE, a PEO, a post-reorder module, and one TMEM. The TMEM is implemented using 64-word 12-bit dual-port registers and has a latency of 52-cycles. Based on the time scheduling strategy a hardware utilization of maximum can be achieved.

V. CONCLUSION

2-D DCT core employs a single 1-D DCT core and one TMEM with a small area. The 8-bit DA precision is chosen in order to meet the PSNR requirements and the hardware sharing architecture enables sharing based on time so as to reduce area cost.

The number of adders/subtractors in 1-D DCT core allows 74% saving in area over the NEDA architecture for the DA-based DCT design. The system arranges the computation time for each process element. The 1-D core can calculate 1-D and 2-D transformation simultaneously and achieves a high throughput rate. So it has high accuracy, a small area, and a high-throughput rate has achieved using STS strategy. In the future work while using an 8-bit DA precision length will reduce the noise in the image.

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