Design of Automatic Loading Machine in Electroplating Industry

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Abstract: Earlier, in electroplating industries, all the work was done manually. In 1976, the first semi-automatic plant was set up in India. Thus the electroplating industry has taken a big jump after the introduction of automatic plants. However, there are some tasks which are still being done manually and result in more use of labour leading to inefficiency and tedious work. One of these tasks is loading of barrel. This paper includes the design of automatic loading machine and various components required for the automatic weighing and loading of material into the barrel. It also includes the financial cost analysis of the machine and thus, the break even time of the machine. It concludes with the benefits of using this automatic loading machine over manual loading.

Keywords: Electroplating, material, loading, barrel, cost

I. INTRODUCTION

A. Field

Metals are predominantly being used in almost every aspect of our day to day lives. However, one of the major problems in metals is corrosion i.e. gradual destruction of metal by oxidation i.e. chemical reaction with oxygen present in the environment. Thus, a special branch called corrosion engineering has been designed to study the prevention of corrosion. Especially, in automobiles, the chances of metal parts getting corroded are high due to the working conditions. The most widely used method for prevention of corrosion in automobiles is plating. Plating is a surface coating chemical process in which a metal is deposited on another metal having a conductive surface.

Plating is one of the major processes in corrosion resistance. The advantages of plating include:

- Protection from corrosion
- Appearance
- Superior Hardness and Better Wear Resistance

B. Background

An electroplating process involves a series of chemical reactions with different chemicals to achieve the final result. In industries, these reactions take place in tanks containing the chemicals. The parts that need to be plated need to be kept in one tank for a decided amount of time in which the reaction takes place. After a particular reaction it needs to be transferred from one tank. This process continues until the last tank is reached and all chemical reactions have taken place.

The two types of electroplating industries include:

1) Manual Plant: Manual plant is a plant in which transfer of work between tanks is by hands. The parts are

- immersed in tanks manually and held for a particular period of time before transferring to next tank.
- 2) Automatic Plant: An automatic plating plant is a line of process tanks with a transfer system which enables the parts to be plated to be immersed in each tank for the appropriate time and in the sequence necessary to produce the required finish.

C. Scope

Manpower is a major factor in any industry. However excessive use of manpower can lead to reduction in efficiency, increase in total production cost due to salary of manpower, decrease in production and inconsistent quality. In many industries, one more important requirement is skilled labour. Also, the salaries of labour are increasing every year due to inflation. Thus, the main aim in any industry in today's world is to reduce manpower and introduce the use of machines wherever possible to increase the efficiency of working.

These issues can be taken care of by conversion of manual plating plant to automatic. However, even in automatic plants, the loading and unloading of parts on barrel takes place manually. At one time, 100 kg of material is to be weighed and loaded which is a very tedious task. This results in increase in labour and thus decreases the efficiency. Thus, one more major problem is how to transform manual loading of barrels to automatic loading in an automatic plating plant.

II. AUTOMATIC LOADING MACHINE

The Automatic Loading Machine is intended to give an output of a pre-defined quantity of material as per the set weight. Electroplating is a surface treatment phenomenon based on the surface area of the material. However surface area of a material is very difficult to measure. This surface area can be converted to weight by a suitable conversion factor obtained experimentally. Thus the required output can be achieved by setting a weight limit. Thus, the Automatic Loading Machine transports the component to the height of the barrel and loads the material according to the weight.

A. Construction

The Automatic Loading Machine can be divided into two sections:

1) Loading Conveyor Section

This section transfers the material from bottom to the height at which it has to be loaded in the barrel. It consists of:

Hooper: It is used to store the material which has to be loaded on the barrel before transportation by the conveyor. It is a storage tank/pit located at the one end of the conveyor.

- Slat Belt: It is the belt of the conveyor section which is used to transfer materials to the other end located at the top. This belt is further divided into compartments to facilitate lifting and transfer of material.
- Conveyor Roller: It is used to run the slat belt. The roller is powered by gear box which is powered by the motor. Thus the roller runs the slat belt with a speed according to our requirements.
- Motor: Motor gives required power to the gear box which is used to run the roller.
- Gear Box: It is used for reduction of the speed and increase in torque received by the motor according to requirement of the belt.
 - 2) Weighing and Transfer Trolley Section

This section does the weighing of the material and actual loading to the barrel by pneumatic push. It consists of:

- Pneumatic Cylinder: The cylinder is used to push the trolley forward towards the barrel for loading. When it receives a signal from the system it is actuated.
- Solenoid Valve: When the weight limit is reached, the signals given to stop the belt and start the cylinder are actuated by solenoid valves.
- Load Cell: It is located inside the trolley and is used to weigh the material entering the trolley. Once the weight limit is reached the system sends signals to conveyor to stop and pneumatic cylinder to start
- Trolley: The trolley is used to transfer the material from the receiving point to distance where it is loaded onto the barrel. The shape of the trolley facilitates direct transfer of material to the barrel.
- Compressor: It is used to supply compressed air for actuating the cylinder. The compressor is also used for various other processes like drying in an electroplating industry.

TABLE I. SPECIFICATIONS OF COMPONENTS OF AUTOMATIC LOADING MACHINE

Conveyor Section					
Sr.No.	Part	Selection Basis	Parameters	Value / Type	
1	Hooper	Capacity of Material to be stored	Material	Mild Steel	
			Length	1200 mm	
			Width	1000 mm	
			Height	1000 mm	
			Thickness	5 mm	
			Storage Capacity	600 kg	
2	Slat Belt	Available Space	Total distance	3600 mm	
			Length	7200 mm	
			Width	450 mm	
			Thickness	10 mm	
			Number	2	
			Material	Mild Steel	
			Number of Compartments	8	
3	Conveyor Roller	Dimensions of Belt	Diameter 150 mm		
			Length 450 mm		
			Material	Mild Steel	
4	Motor	Calculations for selection of motor	Power Rating 1.5 HP		
			Rated RPM	960 RPM	
5	Gear Box	Available Motor Specifications	Gear Ratio	36	

		Weighing and Transfer Trol	ley Section	
Sr.No.	Part	Selection Basis	Parameters	Value / Type
1	Pneumatic Cylinder	Calculations for selection of cylinder	Bore Diameter	54 mm
			Rod Diameter	20 mm
			Stroke Length	1000 mm
2	Pneumatic Solenoid	Standard specifications available	Type 1	5/3 Solenoid Valve
			Type 2	5/2 Solenoid Valve
3	Load Cell	Required output weight	Capacity	1500 mm
4	Trolley	Capacity of material to be loaded	Material	Mild Steel
			Length	700 mm
			Width	600 mm
			Height	450 mm
			Thickness	5 mm
			Capacity	150
5	Compressor	Required discharge pressure	Power Rating	10 HP
			Discharge Pressure	4 bar

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B. CAD Drawing

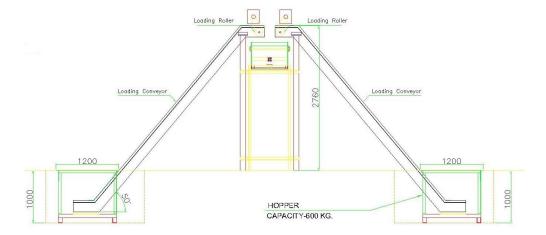


Fig. 1 . Front view of Machine

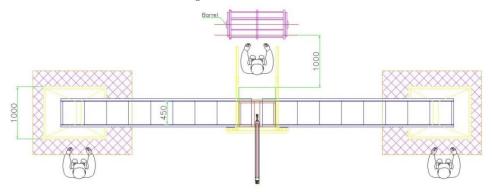


Fig. 2. Top view of Machine

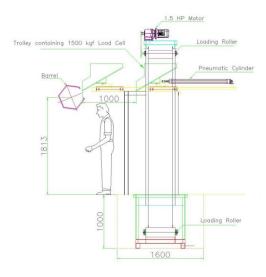


Fig. 3. Side view of Machine

C. Working

The working of the Automatic Loading Machine can also be divided as per two sections:

1) Loading Conveyor Section

The material which is received is transported to the hooper manually. The conveyor belt which runs on the rollers, collects the material from the hooper in different compartments. The material collected in each compartment is calculated by experimentation. The rollers are powered by the gearbox, which is eventually powered by the motor. These materials are transferred to a height at which barrel is placed and then transferred into a trolley

2) Weighing and Transfer Trolley Section

The material placed in the trolley is weighed by using load cell. When the weight reaches the set limit, the system gives a signal to switch off the motor and stop the conveyor. It also actuates the pneumatic cylinder by the solenoid valve to push the trolley forward. The material is carried forward by the trolley thus emptied in the barrel and taken for further processing.

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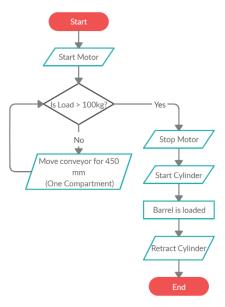


Fig.4. Flowchart showing working of automatic loading machine

III. CALCULATIONS

A. Selection of Motor

1) Motor RPM

Electroplating is a surface treatment phenomenon. Therefore, the capacity of barrel depends on surface area. Each barrel has a capacity of electroplating 100sq.ft. material. However, as mentioned above it is difficult to measure surface area. Thus, this surface area is converted to weight using a suitable factor which is obtained experimentally.

The surface area of one part is measured and various such parts are placed in a vessel whose weight is measured. This is how the weight can be found. According to industry standards, the conversion factor is considered as 1sq.ft. = 1 kg.

Thus, capacity of the barrel is 100 kg. Loading is done every minute. Therefore, output required is 1 kg/min.

To find the effective loading, we need to find the volume of each compartment and thus find the mass in it.

Volume of each compartment can be found as,

Length of each compartment = $l_{compartment} = 450 \text{ mm}$ Breadth of each compartment = $b_{comparment} = 450 \text{ mm}$ Height of each compartment = $h_{compartment} = 40 \text{ mm}$

Therefore, Volume of each compartment

 $V_{comparment} = l_{comparment} \times b_{comparment} \times h_{comparment} =$ $8100000 \text{ mm}^3 = 8.1 \text{ litre}$ $(1 \text{ litre} = 1000000 \text{mm}^3)$

Another experiment is performed to find the weight of material occupied in a 1 litre vessel. It is found from this experiment that a 1 litre vessel occupies 3kg of material. This value is different for different parts.

Also, due to the shape of the part, when the conveyor moves up, it cannot occupy its complete volume with material. According to industry standards and experiments conducted, it is found that around 50% of each compartment of the belt can be loaded.

Therefore, effective loading of each compartment can be found as,

$$m_{\text{effective}} = V_{\text{compartment}} \times \text{Conversion factor} \times \text{Effective}$$

loading factor = 12.15 kg (2)

There are 8 compartments of 450 mm length present on the 3.6 meter belt. Therefore, total mass of all material,

$$m_{material} = m_{effective} \times No. \text{ of compartments} = 97.2 \text{ kg}$$
 (3)

 $m_{\text{material}} = 100 \text{ kg (approx.)}$

Therefore, time required for loading of material can be calculated as,

t = Output required (kg/min) / Input mass of material

$$= 1 \min = 60 \sec \tag{4}$$

Therefore, in this time the whole belt needs to move up, thus distance travelled will be equal to length of the belt.

Length of belt = 3600 mm = 0.36 m

Velocity of the belt can therefore be found as,

$$v_{belt} = l_{belt}/t = 0.06 \text{ m/s} = 3.6 \text{ m/min}$$
 (5)

(1 m/s = 60 m/min)

The roller takes one complete revolution when the belt travels the distance equivalent to its length. The speed of the roller in RPM can be found as,

$$RPM_{roller} = v_{belt} / d_{roller}$$
 (6)

Diameter of roller = 150 mm = 0.15 m

Therefore, $RPM_{roller} = 24 \text{ rpm}$

Consider the value of gear ratio to be 40.

We know that, Gear Ratio = $RPM_{motor} / RPM_{roller}$ (7)

Thus, the rated RPM of motor is,

 $RPM_{motor} = 960 \text{ rpm}$

2) Motor Torque

For finding the value of torque, we need to know the forces, which in turn are calculated from the mass of all components of the machine and the mass of material. The value of mass for all components is found in the table below by using the formula

Mass = Volume
$$\times$$
 Density
Density of Mild Steel = 7.85 g/cm³
(8)

Mass of Belt:

$$\begin{aligned} \text{Volume of belt} &= l_{belt} \times b_{belt} \times h_{belt} = 7200 \times 450 \times 10 \\ &= 32400000 \text{ mm}^3 = 32400 \text{ cm}^3 \\ &\qquad \qquad (1 \text{ cm}^3 = 1000 \text{ mm}^3) \end{aligned}$$

Mass of belt = 254340 g = 254.34 kg

Mass of Roller:

Volume of roller =
$$\pi \times (r_{roller})^2 \times l_{roller} = \pi \times (75)^2 \times 450$$

= 7948.125 cm³

Mass of roller = 62392.78125 g = 62.393 kg

Mass of both rollers = 124.786 kg

Mass of Slat Chain

Length of Slat Chain = 7.2 m

Mass per unit length = 4.4 kg/m

(Standard factor of conversion)

Mass of chain = 31.68 kg

Mass of material = 100 kg

Therefore, total mass of all components = 510.806 kg

The total force to be pulled by the conveyor can be calculated by the free body diagrams given below where,

 $m = m_{material}$, $M = Total Mass of all components, <math>\Theta =$ 50° , Coefficient of friction between belt and material = μ_1 = 0.15, $g = 9.81 \text{ m/s}^2$

(1 kg = 1000 g)

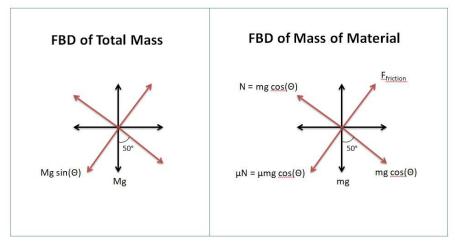


Fig. 5. Free Body Diagram of System

Therefore.

$$F_1 = Mg \sin(\Theta) + \mu_1 mg \cos(\Theta)$$

$$F_1 = 3931.861 \text{ N}$$
(9)

Considering a factor of safety of 1.5, the total force can be thus calculated as,

$$F = F_1 \times FOS \tag{10}$$

F = 5897.792 N

Torque is given by the formula,

$$T_{\text{roller}} = F \times r_{\text{roller}} \tag{11}$$

where, $r_{roller} = 75 \text{ mm} = 0.075 \text{ m}$

Therefore, $T_{roller} = 442.334 \text{ N-m}$

We know that,

Gear Ratio =
$$T_{roller} / T_{motor}$$
 (12)

Thus, the rated torque of motor is,

$$T_{\text{motor}} = 11.058 \text{ N-m} = 11 \text{ N-m (approx.)}$$

3) Motor Power

Power is given by the formula,

$$P_{\text{motor}} = T \times \omega = T \times [(2\pi \times RPM) / 60]$$
 (13)

Therefore, $P_{motor} = 1111.144 \text{ Watt} = 1.111 \text{ kW} = 1.489 \text{ HP}$ (1 HP = 746 Watt = 0.746 kW)

Therefore, $P_{motor} = 1.5 \text{ HP}$

B. Selection of Pneumatic Cylinder

The selection of dimensions of cylinder can be done on the basis of the formula

Push Force = Discharge Pressure × Area of Cylinder

$$F_{push} = P_{discharge} \times A_{cylinder}$$
 (14)

Mass of the material to be pushed,

 $m_{\text{material}} = 100 \text{ kg}$

Mass of trolley can be calculated as,

Length of trolley = $l_{trolley}$ = 700 mm

Breadth of trolley = $b_{trolley}$ = 600 mm

Height of trolley = $h_{trolley} = 450 \text{ mm}$

Thickness of trolley = $t_{trolley} = 5 \text{ mm}$

Total Surface Area of trolley = $A_{trolley} = I_{trolley} \times h_{trolley} +$ $b_{trolley} \times h_{trolley} + b_{trolley} \times l_{trolley}^2 \times h_{trolley}^2$) = 1084299.5093

Volume of trolley = $V_{trolley} = A_{trolley} \times t_{trolley}$

$$= 5421497.5466 \text{ mm}^3 = 5421.4975 \text{ cm}^3 (16)$$

 $(1 \text{ cm}^3 = 1000 \text{ mm}^3)$

Density of Material = $d_{\text{mildsteel}} = 7.85 \text{ g/cm}^3$

Therefore, Mass of trolley =
$$m_{trolley} = V_{trolley} \times d_{mildsteel} = 42558.756 g = 43 kg$$
 (17)

Therefore, total mass to be pushed by the cylinder,

 $m_{total} = m_{material} + m_{trolley} = 143 \text{ kg}$

Push force required will be equal to the frictional force between bottom surface of the trolley and the surface on which it is pushed.

Coefficient of friction = $\mu_2 = 0.5$

Acceleration due to gravity = g = 9.81

$$F_{\text{push}} = \mu_2 \text{mg} = 701.415 \text{ N} \tag{18}$$

Discharge pressure of the cylinder which is selected is,

 $P_{discharge} = 4 \text{ bar} = 0.4 \text{ N/mm}^2$

Area of cylinder can be calculated as:

$$A_{\text{cylinder}} = F_{\text{push}} / P_{\text{discharge}} = 1753.5375 \text{ mm}^2$$
 (19)

Area of cylinder can be given by the formula:

Area of Cylinder =
$$3.14*(D^2 - d^2)/4$$
 (20)

where, D = bore diameter, d = rod diameter

In standard cylinders available, Rod diameter = 20 mm

Therefore, Bore diameter can be calculated as,

$$D^2 = [(4*Area of cylinder)/3.14] + d^2$$
 (21)
D = 51.321 mm

Selecting from the standard sizes available,

Bore Diameter = 54 mm.

The cylinder needs to push the trolley upto a required distance at which the barrel is to be loaded.

Therefore, stroke length of the cylinder should be equal to the distance through which the trolley travels. According to space considerations the barrel is located at 1 meter for the starting point.

Therefore stroke length of the cylinder,

L = 1000 mm

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IV. FINANCIAL ANALYSIS

A. Cost of Machine

TABLE II. CALCULATION OF COST OF MACHINE

Component	Price (Rs.)	Remark	
	`	4.5 YP. 0.50 P.P. 4	
Motor	8500	1.5 HP, 960 RPM	
Gear Box	10000	Gear Ratio = 36	
Pneumatic	17000	Stroke Length = 1000 mm, Bore	
Cylinder		Diameter = 54 mm	
Compressor	40000	Discharge Pressure = 4 bar, 10 HP	
Slat Belt & Chain	72000	14.4 meters belt	
Conveyor Roller	18000		
Pneumatic	11000	5/2 and 5/3 Solenoid Valve	
Solenoid			
Hooper	52800	440 kg Mild Steel sheet of 5 mm	
•		thickness	
Trolley	5160	43 kg Mild Steel sheet of 5mm thickness	
Load Cell	25000	Max Capacity 1500 kgf	
SCADA	15000		
Other Misc.	20000		
TOTAL	294460		

B. Labour Cost

TABLE III CALCIII ATION OF LABOUR COST

TABLE III. CALCULATION OF LABOUR COST			
Type	Manual	Automatic	
Total Labour	6	2	
Daily Wages	450	450	
No. of Shifts	3	3	
Daily Labour Cost	8100	2700	
Annual Labour Cost	2430000	810000	

*(Considering 1 year has 300 working days)

D. Total Annual Savings

For Manual Loading,

Total Annual Cost = Annual Labour Cost = Rs.2430000

For Automatic Loading,

Total Annual Cost = Annual Labour Cost + Annual Power Consumption + Cost of Machine = Rs.1215017

Thus the total annual cost for automatic loading is approximately equal to 50% of manual loading annual cost.

Therefore, Total Annual Savings = Rs.1214983

Break Even Time of Machine

The total cost incurred by manual and automatic loading can be classified into two parts: Fixed and Variable. Fixed cost includes the cos of the machine which is constant throughout, whereas, variable cost includes the costs incurred daily which are labour and electricity cost.

The total cost incurred upto 'n' days can be calculated by the formula.

> Total cost = Fixed Cost + (Variable cost per day \times n) where, Fixed Cost = Cost of Machine and Variable Cost = Daily Labour Cost + Daily **Electricity Cost**

For Manual Loading,

Fixed Cost = 0, Daily Electricity Cost = 0

Therefore, Total Cost = $n \times Daily Labour Cost = n \times 8100$ For Automatic Loading,

Fixed Cost = Machine Cost = Rs.294460

Variable Cost per day = Daily Labour Cost + Daily Electricity Cost = Rs.2983.48 per day

C. Power Consumption

TABLE V. CALCULATION OF ANNUAL POWER CONSUMPTION

Motor		
Power Rating	1.5	HP
	1.119	kW
Operating time per cycle	2	mins
Cycle time	6	mins
No. of Cycles/Hour	10	cycles/hr
Operating Time per hour	20	mins
	0.333	hours
Power Consumption	0.373	kW-hr
	0.373	units
Rate per Unit	9.5	Rs
Electricity Cost per hour	3.544	Rs.
Electricity Cost per day	85.044	Rs.

Compressor		
Power Rating	10	HP
	7.46	kW
Operating time per cycle	1	mins
Cycle time	6	mins
No. of Cycles/Hour	10	cycles/hr
Operating Time per hour	10	mins
	0.167	hours
Power Consumption	1.243	kW-hr
	1.243	units
Rate per Unit	9.5	Rs
Electricity Cost per hour	11.812	Rs.
Electricity Cost per day	283.48	Rs.
Total Electricity Consumption Per Day	368.52	Rs.
Annual Electricity Consumption	110557	Rs.
**/C '1 ' 1 1	200	1

*(Considering 1 year has 300 working days)

Therefore, Total Cost = $294460 + (2983.48 \times n)$

Considering that after 'x' days the total manual loading cost will be equal to the total automatic loading cost.

 $x \times 8100 = 294460 + (2983.48 \times x)$

x = 57.551 = 58 days (approx.)

Therefore it can be said that after 58 days, the Automatic Loading Machine will start giving profits which will thus keep on increasing. This point is also known as break even time.

The break even time can also be found out graphically. Considering the total cost incurred in Manual and Automatic Loading for a span of 120 days. It can be seen that the breakeven time comes out to be approximately 60 days.

TABLE VI. COST INCURRED BY MANUAL AND AUTOMATIC LOADING FOR 120 DAYS



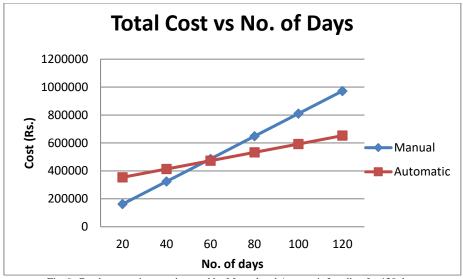


Fig. 9. Graph comparing cost incurred by Manual and Automatic Loading for 120 days

V. COMPARISON BETWEEN MANUAL AND AUTOMATIC LOADING

TABLE VII. COMPARISON BETWEEN MANUAL AND AUTOMATIC LOADING

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Type of Loading	Manual	Automatic	
Weighing	Manual	Automatic	
Dependency on Labour	High	Very Low	
Power Consumption	Not required	Required	
Initial Investment	Low	High	
Long Term Costs	High	Low	
Error	Possible	None	
Efficiency	Low	High	

VI. CONCLUSION

Excess labour can lead to decrease in the efficiency. Also the cost labour is increasing every year by approximately 10% due to increase in rate of inflation. Availability of labour is also going to be a major issue in near future. Therefore, we need to rely on some new machines to increase the efficiency and also reduce the cost.

The automatic loading machine used in electroplating industries for loading of barrel can be introduced to solve the above problems. It can be seen from this report that the machine starts giving profits within only 58 days of instalment. This will reduce the labour cost required resulting in increasing savings every year. Also the efficiency of the work increases. Thus, this machine can be a boost in the electroplating industry.

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