

# Design Analysis & Topology Optimization of Passenger Car Disc Brake

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**Abstract-** The disk brake may be a device for slowing or stopping the rotation of a wheel. Generally repetitive braking system of the automobile cars results in heat generation during each braking event. The brake disc brake 3D model prepared by CATIA software. Finite Element modal analysis of automobile 4 wheeler disc brake is performed to determine mode shapes and natural frequencies and also static analysis is performed to obtain optimized model from topology optimization technique from ANSYS 19 software. Hence, experimental testing using FFT analyzer technique (impact hammer and accelerometer) is performed to determine mode shapes and natural frequency and comparison of results with numerical results.

**Keyword -** Disc Brake, Topology Optimization, FFT Analyzer.

## I. INTRODUCTION

The racing fans involved will surely know the importance of good brakes not just for safety but also for staying competitive. The disk brake may be a device for slowing or stopping the rotation of a wheel. A brake disc usually made from forged iron or ceramic composites includes carbon, Kevlar and silica, is connected to the wheel and therefore the axle, to prevent the wheel. A friction brake generates frictional forces as two or more surfaces rub against one another, to scale back movement. Based on the planning configurations, vehicle friction brakes are often grouped into drum and disc brakes. The main component of the braking system is the disk brake. Its performance directly affects the driving safety of the vehicle. When the vehicle is braking, the excitation frequency is close to the natural frequency of the brake disk, which will cause resonance, generate severe vibration & noise & affect ride comfort. Therefore, it is necessary to analyses modal characteristics of disk brake. TATA Sumo 800 Lacer car disc brake was taken for experimental study purpose. The brake disc (or rotor) is that the rotating a part of a wheel's disk brake assembly, against which the restraint are applied. The material is usually gray iron, a sort of forged iron. The weight and power of the vehicle determines the necessity for ventilated discs.



Fig 1.TATA Sumo 800 Lacer Car Disc Brake

## II.PROBLEM STATEMENT

Nowadays, topology optimization technique is used for weight optimization of components which reduces material cost and manufacturing. In present research 4-wheeler disc brake is to be studied under FEA to determine the optimum material removal from existing 4-wheeler disc brake under existing boundary condition and also determine changes in von misses stress and deformation with tautologized model. Natural frequencies are calculated to determine the nature of mode shapes at respective frequencies

## III.METHODOLOGY

The methodology involves the technology utilized for performing the designing and analysis of the object.

- Design of 4 wheeler disc brake
- Dimension specification
- Analysis of disc brake by ANSYS
- Static structural analysis & Modal Analysis for mode shape.
- To perform static structural analysis of disc brake under existing boundary condition to obtain deformation and von misses stress and optimized model from topology optimization.
- The best optimized is to be obtained from topology optimization technique and compared to the existing model.

#### IV. CAD DESIGN

Design parameters of TATA Sumo 800 Lacer car

- Disc Diameter = 260 mm
- Disc Material = Grey Cast Iron
- Disc Thickness = 12 mm
- Internal Diameter = 140mm
- Internal Thickness = 50 mm
- Hole Diameter = 10 mm 5Holes
- Pad brake Material = Asbestos
- Pad Dimension = 125 mm x 12 mm

Used CATIA software. CATIA is mechanical design software. CATIA users access the highest productivity for specific advanced processes with focused solutions.

- Sketcher
- Part design
- Assembly design
- Wireframe and surface design
- Drafting
- Analysis of disc brake in CATIA
- Meshing Structural Static & Modal analysis by ANSYS software

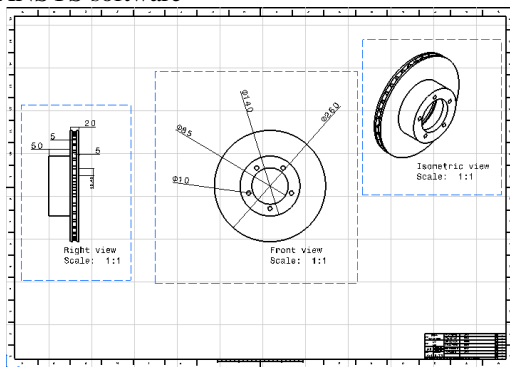


Fig 2 Drafting Of 4 Wheeler Disk Brake

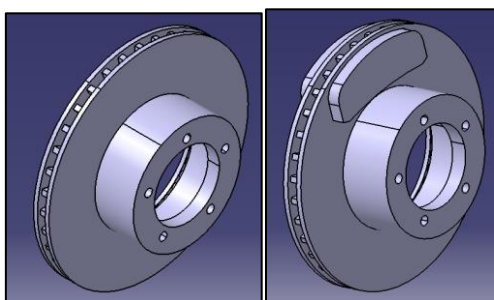


Fig 3 Catia Design of Disc Brake

Properties of Outline Row 3: Gray Cast Iron		
A	B	C
Property	Value	Unit
1		
2	Material Field Variables	Table
3	Density	7200
4	Isotropic Secant Coefficient of Thermal Expansion	
5	Coefficient of Thermal Expansion	1.1E-05
6	Isotropic Elasticity	
7	Derive from	Young's Modulu...
8	Young's Modulus	1.1E+11
9	Poisson's Ratio	0.28
10	Bulk Modulus	8.333E+10
11	Shear Modulus	4.2969E+10

Fig.4 Material Properties of Disc Brake

#### V. DESIGN CALCULATION

Input Parameter for Disc Brake of TATA Sumo 800 Lacer

Parameter Name	Parameter Value (Unit)
Mass of Vehicle	2625 Kg
Speed of Vehicle	100 km/h = 27.7 m/s
Wheel Diameter	600 mm
Wheel Base	2425 mm

Table 1: Basic Parameter of Vehicle

Parameter Name	Grey Cast Iron
Density	7000 Kg/m <sup>3</sup>
Yield Tensile Strength	142 MPa
Young Modulus E	100 GPa
Poisson Ratio v	0.28
Specific Heat, C <sub>p</sub>	586 J/Kg.K
Thermal Conductivity ,K	54 W/m.K

Table 2: Properties of Grey Cast Iron

Parameter Name	Parameter Value
Outer Diameter of Disc	260 mm
Inner Diameter of Disc	140 mm
Hole Diameter	10 mm
Thickness of Disc	12 mm
Weight of Disc	6.2 Kg

Table 3: Disc Brake Dimensions

#### Calculation:

##### a) Kinetic Energy of Vehicle

$$K.E = (M \times V^2) / 2 = (2625 \times 27.7^2) / 2$$

$$K.E = 1007068.125 \text{ Joule}$$

Where,

K. E – kinetic Energy (J)

M – Mass of vehicle (Kg)

V – Linear velocity of vehicle (m/s)

##### b) Stopping distance of vehicle

Braking distance of vehicle refers to the distance a vehicle will travel from the point when its brakes are fully applied to when it comes to a complete stop.

The maximum friction force F [4]

$$F = \mu * M * g$$

$$= 0.7 * 2625 * 9.81$$

$$0.7 [2]$$

$$F = 18025.8 \text{ N}$$

##### c) Deceleration of the vehicle:

$$a = F/M$$

$$= 18025.8 / 2625$$

$$= 6.86 \text{ m/s}^2$$

##### d) Time taken to stop the vehicle:

$$t = V/a$$

$$= 27.7/6.86$$

$$t = 4.037 \text{ s} \approx 4 \text{ s}$$

##### e) Distance cover

Maximum speed of vehicle is 27.7 m/s

So, distance covered by vehicle in 4 second is =  $27.7 \times 4$

Stopping distance (SD) = 110.8 m

Now, following is other equation to calculate total stopping distance by considering reaction time of driver is [4]

Total Stopping distance (SD)

$$SD = (V \times \text{reaction time}) + (V^2 / 2 * \mu * g)$$

$$= (27.7 \times 4) + (27.7^2 / 2 \times 0.7 \times 9.81)$$

$$SD = 138.96 \text{ m}$$

So, by considering the average stopping distance is 124 m.

#### f) Breaking force

Brake force, also known as Brake Power, is a measure of braking power of a vehicle.

Here following process is given to calculate exact force required to stop vehicle within stopping distance or stopping time. [4]

Tangential braking force: (BF)

$$(BF)t = K \cdot E / (SD) \quad \dots (S D - \text{stopping distance})$$

$$= 1007068.125 / 124$$

$$(BF)t = 8121.51 \text{ N}$$

Tangential force on each wheel Ft

$$Ft = (BF) / 4 \quad \dots (4 \text{ indicate force on each wheel})$$

$$= 8121.51 / 4$$

$$= 2030.3 \text{ N}$$

Braking torque on wheel Tw

$$Tw = Ft \times R$$

$$= 2030 \times 0.300$$

$$= 609 \text{ N.m}$$

Where, R – Radius of the tyre (m)

Effective Rotor radius Re

$$Re = (\text{Rotor diameter} / 2) - (\text{caliper piston diameter} / 2)$$

$$Re = (260 / 2) - (44 / 2) \quad \dots (\text{Rotor diameter} - 260 \text{ mm})$$

$$Re = 103 \text{ mm} = 0.103 \text{ m}$$

Here, caliper piston diameter is 44 mm.

#### g) Braking torque on disc Tb

$$Tb = Tw \times R / r$$

$$= 609 \times 250 / 125 \quad \dots (Tw - 250 \text{ mm})$$

$$Tb = 1218 \text{ N.m}$$

#### h) Clamping force C

$$C = Tb / 2 \times \mu \times Re$$

$$= 1218 / 2 \times 0.5 \times 0.103$$

$$C = 11825 \text{ N}$$

Pressure applied by clamp force on pad = clamping force / area of pad

$$= 11825 / 5145.6 \quad (\text{Area of pad} - 5145 \text{ mm}^2)$$

$$= 2.29 \text{ MPa} \quad \dots (A) [4]$$

### VI. ANALYSIS

TATA Sumo 800 Lacer car disc brake is taken for analysis.

After designing disc brake rotors in CATIA V5 the profiles is imported to ANSYS Workbench for further analysis such as Static structural analysis, and Modal analysis.

#### Material Selection for Disc Brake – Grey Cast Iron

Properties of Outline Row 3: Gray Cast Iron			
	A	B	C
1	Property	Value	Unit
2	Material Field Variables	Table	
3	Density	7200	kg m <sup>-3</sup>
4	Isotropic Secant Coefficient of Thermal Expansion		
5	Coefficient of Thermal Expansion	1.1E-05	C <sup>-1</sup>
6	Isotropic Elasticity		
7	Derive from	Young's Modulus...	
8	Young's Modulus	1.1E+11	Pa
9	Poisson's Ratio	0.28	
10	Bulk Modulus	8.333E+10	Pa
11	Shear Modulus	4.2969E+10	Pa

Fig.5 Engineering Material Properties in ANSYS

#### Geometry of Existing Disc Brake

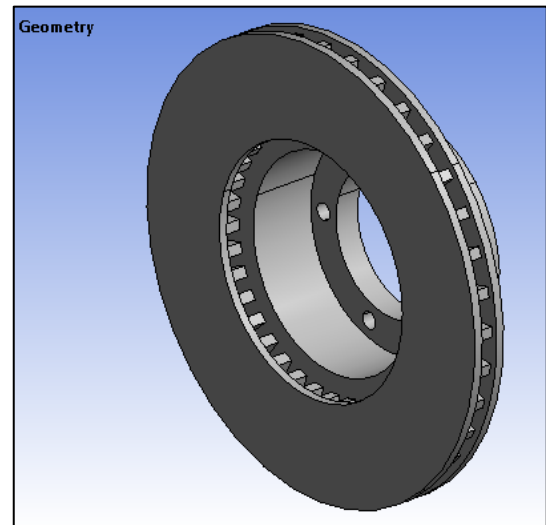
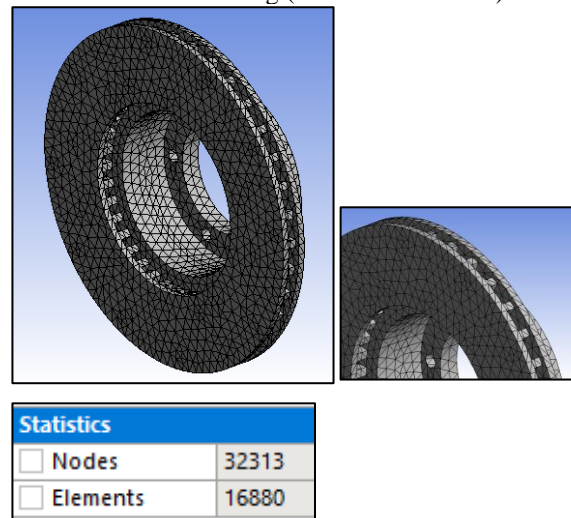


Fig. 6 Geometry of Disc Brake Imported In ANSYS

#### Meshing

Meshing done by ANSYS software to reduced degree of freedom from Infinite to finite with the help of discretization or meshing (Nodes & Elements)



Statistics	
<input type="checkbox"/> Nodes	32313
<input type="checkbox"/> Elements	16880

Fig. 7 Details of meshing

#### Boundary Conditions

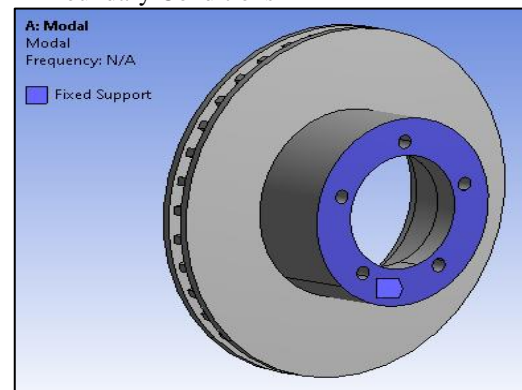


Fig. 8: Boundary Conditions for Disc Brake-MA

Disc brake is fixed at one end to determine the mode shape and natural frequency.

### • Modal Analysis:

Modal analysis may be a technique to review the dynamic characteristics of a structure under vibrational excitation. Natural frequencies, mode shapes and mode vectors of a structure may be determined using modal analysis.

### Different Mode Shapes:

The modal frequencies of the first five steps and modal shapes of each order shown in below figures:-

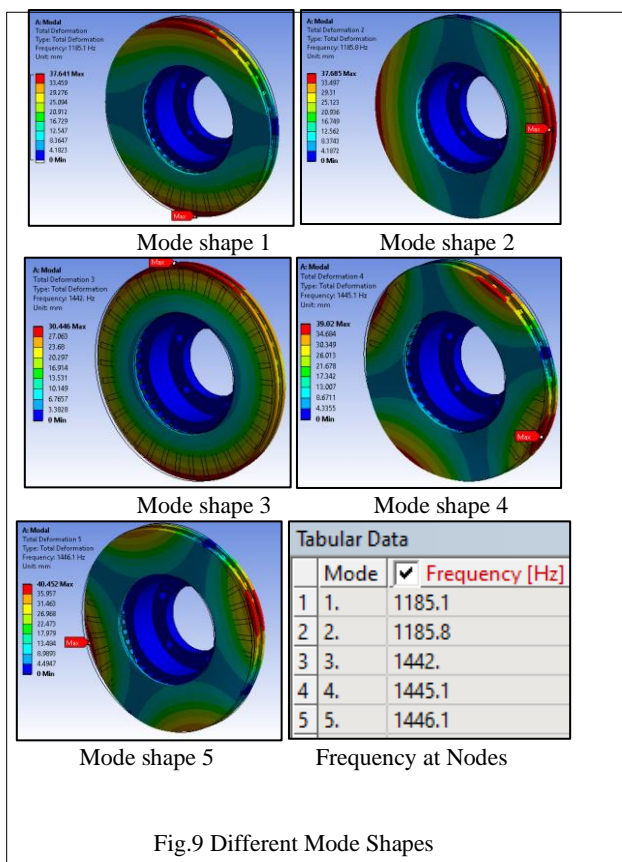


Fig.9 Different Mode Shapes

In above figures different mode shapes are plotted with respective natural frequency so, it is observed the mode shape pattern also change with respective frequency so maximum frequency is observed around 1446 N.

### • Static Structural Analysis

Consider Velocity of Vehicle (V) = 80 km/hr = 22.22 m/s

Where,

V– Velocity of Vehicle

Diameter of Disc brake (d) = 0.26 m

Radius of Disc Brake (r) = 0.13 m

$V = r \times \omega$  ..... ( $\omega$  – Angular velocity)

$22.22 = 0.13 \times \omega$

$\omega = 170 \text{ rad/s}$  [4]

In above analytical calculation (A) pressure acting on pad is calculated as 2.29 MPa but design is for maximum condition so standard equation to calculate pressure on pad is given below

From paper mentioned standard equation is

$$P(t) = 4 \times 10^6 \cdot \left(1 - e^{-\frac{t}{0.001}}\right)$$

$$\omega(t) = 69.44 - 22.32 \cdot \left(t + \frac{3.274}{20} e^{-\frac{t}{0.001}} - \frac{3.274}{20}\right)$$

So, pressure on rubber pad is 4 MPa on both sides are applied.

So, we have 4 MPa and 2.29 MPa as per design. It is beneficial to use 4 MPa as design should sustain extreme pressure due to fluctuation of motion on disc brake.

### • Boundary Condition:

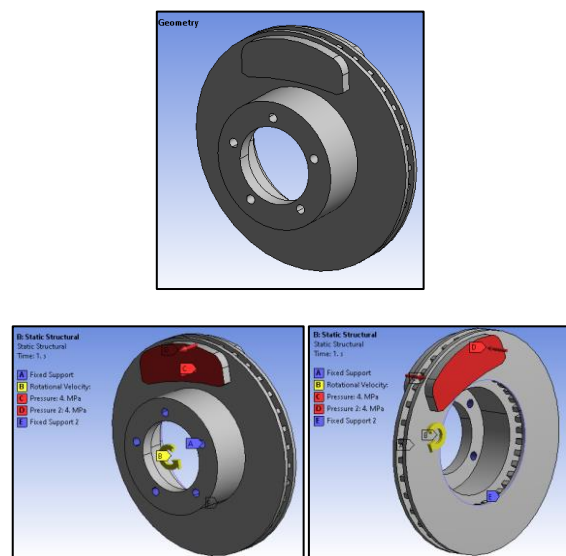


Fig.10 Details of Boundary Conditions-SA

- In boundary condition following are forces, pressure is mentioned.
- Fixed support is applied along circular bolt holes and across edges as per existing situation.
- Pressure of 4 MPa as per calculated analytically is applied on both surface of caliper pad as shown in red region.
- Rotational velocity of 170 rad/s = 80 km/h is applied indicated in yellow region.

### • Total Deformation Results

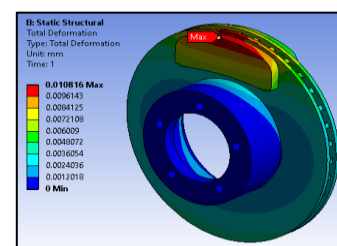


Fig.11 Total Deformation Results



It is observed that maximum deformation is 0.0108 mm.

### • Equivalent Stress Results

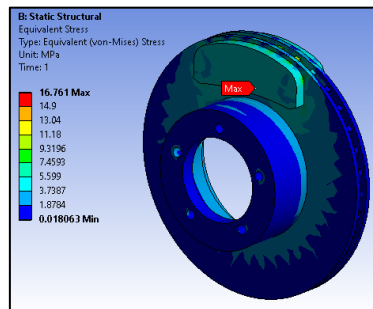


Fig. 12 Equivalent Stress Results

Maximum stress observed is 16 MPa

### VII. TOPOLOGY OPTIMIZATION

Topology optimization could also be a mathematical approach that optimizes material layout within a given design area, for a given set of loads and boundary conditions such the resulting layout meets a prescribed set of performance targets.

Basic Theory

There are three types of structure optimization,

- Size optimization
- shape optimization
- Topology optimization

Three optimization ways in which correspond to the three stages of the merchandise design methodology, significantly the detailed design, basic design and conceptual design. Size optimization keeps the structural form and topology structure invariant, to optimize the varied parameters of structure, like thickness, section size of beam, materials properties; shape optimization maintains the topology structure, to vary the boundary of structure and form, explore for the foremost applicable structure boundary scenario and shape; topology optimization is to hunt out the foremost effective path of materials distribution throughout never-ending domain that meet the displacement and stress conditions in structure, produce a specific performance optimum. Thus, compared to size and shape optimization, topology optimization with more freedom degree and bigger design area, its greatest feature is below unsure structural form, keep with the well-known condition and a given load to work out a budget structure, every for the abstract sort of recent product and improvement design for existing product, it is the foremost promising side of structural optimization. For continuous structure topology optimization, there are some mature ways like: uniform technique, evolutionary structural optimization technique, variable density technique etc. Uniform technique introduced cell structure of micro structure (unit cell) at intervals the weather of the structure, each unit has three forms, significantly non-material voids (size = 1), isotropic-material entity medium (size = 0) and orthotropic-material opening-hole medium ( $0 < \text{size} < 1$ ). whereby the distribution of every form are able to describe the shape of topology and conjointly the shape of structure; evolutionary structural optimization technique believe that

stress in any elements of the structure should beneath the identical level in a perfect structure thus you will be able to delete the fabric artificially.

Thus bit by bit remove material that in a very low stress state, then delete the update rate, thus optimized structure becomes more uniform.

Variable density technique is employed to conduct optimization throughout this paper.

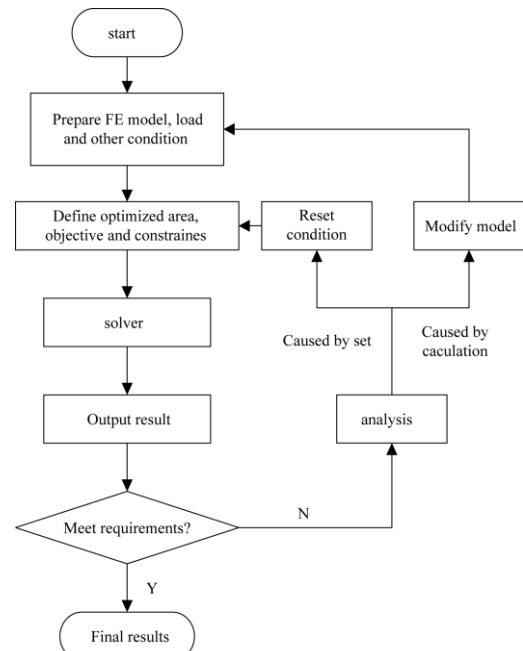


Fig.13 Process of Topology Optimization

### • Boundary Condition

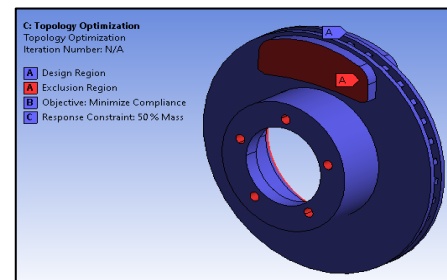
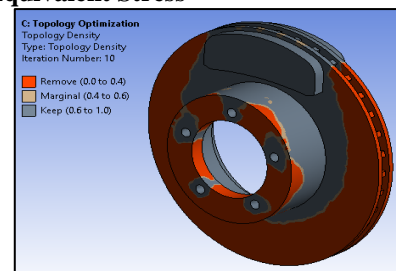


Fig. 14 Boundary conditions for topology optimization

In boundary condition of topology optimization exclusion region are boundary condition applied in static structural analysis these are excluded.

### • Equivalent Stress



Original Mass	6.2865 kg
Final Mass	3.4915 kg
Percent Mass of Original	55.539

Fig. 15 Topology Optimization Results

## VIII. EXPERIMENTAL TESTING

The experimental validation operation is finished by using FFT

Operation testing (Fast Fourier Transform) analyzer. The FFT spectrum analyzer samples the input, computes the magnitude of its sine and cosine components, and displays the spectrum of these measured frequency components. The advantage of this system is its speed. Because System operation FFT spectrum analyzers measure all frequency components at identical time, the technique offers the likelihood of being persistently faster than traditional analog spectrum analyzers. This analysis will be expressed as a series operation. The fast Fourier transform could be a method of operation mathematical method for transforming a function of your time into a function of frequency. Sometimes it's described as system transforming from the time domain to the frequency domain. it's very useful for all method analysis of time-dependent.

### FFT analysis

FFT is one main property in any sequence getting used generally. To find this property of FFT for any given sequence, many transforms are being employed. the most important issues to be noticed find this property are the time and memory management. Comparison is finished between the 2 algorithms with relevance the memory and time managements and therefore the better one is pointed. Comparison is between the two algorithms written, considering the time and memory because the sole main constraints. Time taken by the 2 transforms find the basic frequency is taken. At the identical time the memory consumed while using the 2 algorithms is additionally checked. Supported these aspects it's decided which algorithm is to be used for better results.

## IX. SUMMARY

- ✚ Modal analysis of hydraulic brake is performed to get different mode shapes and natural frequency of existing 4-wheeler hydraulic brake.
- ✚ Static structural analysis of hydraulic brake is performed to see deformation and equivalent stress. It's observed around maximum deformation is 0.0108 mm and equivalent stress is 16.76 MPa.
- ✚ It's concluded that the region indicated in the pit in topology optimization provides information regarding removal of material from that area it's about 55.53% to original mass.

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