Condition Monitoring of a Dynamic System using Artificial Intelligence

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Abstract—Several machines consist of multiple rotating mechanisms, some of which are very complex and critical for operation. These rotating components give out vibrations during operation. Different components of the machine have different natural frequency of vibration. Here we have considered three source of vibrations – bearing failure, unbalanced mass and misalignment of shaft. If the amplitudes of these vibrations surpass the limiting value, it indicates the abnormal behaviour of the machinery and might cause severe damage. It is essential to identify the source of vibration that lead to failure of machine. An effective diagnostic system is needed to predict the condition and reliable lead time of the machine. In this study, Tri-Axial accelerometer is used to sense vibrations of the machine. If the vibration deviates from the standard value that is the natural frequency of vibration, the transducer measures that and it sends the data to the controller which selects the dominating amplitude and frequency and transmits these data to Artificial Intelligence (AI) code wirelessly using Ethernet. These received data is processed by Naïve Bayes Algorithm which uses probabilistic approach to predict the exact source of vibration.

Keywords: Predictive Maintenance, Condition Monitoring, Abnormal Vibrations, Tri-Axial accelerometer, Artificial Intelligence, Multinomial Naïve Bayes algorithm.

I. INTRODUCTION

The principle of this study is that every dynamic mechanism vibrates periodically when in isolation, however when there happen to be multiple dynamic motions in the same setup simultaneously, the periodicity of the vibration pattern is disrupted and the resultant vibrations are obtained. If the vibration exceeds the threshold, they may become detrimental and would affect the performance of the machine, also it would not be easy to figure out exactly which of the components is causing such anomalous vibrations.

Predictive Maintenance

Failures occurring in the machines may be expensive and also affects the overall working of the equipment. Repairing or replacing such components frequently on its failure is tedious, time consuming and a lot of capital is spent on the testing and maintenance of it. Safety being a major concern, routine checking of the setup is too required. Predictive Maintenance (PdM) is a process for monitoring equipment during operation in order to identify any deterioration, enabling maintenance to be planned thus reducing the operational cost [1]. Vibration based condition monitoring can be used to detect and diagnose machine faults and form the basis of a Predictive Maintenance strategy [2].

Industrial Vibration Analysis

Industrial vibration analysis is a measurement tool used to identify, predict, and prevent failures of rotating machinery in heavy industries like paper cutting, iron and steel, textile industry and many other production industries [7]. Applying the analysis of vibration onto the equipment can ameliorate reliability of the machines, improvise the efficiency and minimize the failure rate [3]. Condition monitoring is used in heavy industries where blowers, atomizer, motor bearings, gearboxes, rotors are used.

Source of Vibration

Defect in the bearings is one of the sources of vibration in the machinery. Bearing defects may be due to excessive load, loose or tight fits [16].

Another source of vibration in the machinery is unbalanced mass condition. In this condition, the mass around the axis of rotation is unequally distributed. This results in unbalance forces acting on the system, leading to excessive vibrations. Other source of vibration considered in this study is misalignment of shaft which is caused due to looseness of nut and bolt leading to abnormal vibrations. Under operation, such defects could lead to severe damage.

II. ABBREVIATIONS AND ACRONYMS

MEMS Micro-Electro-Mechanical Systems

PdM Predictive maintenance

VBR Vibration

SFD Shear force theory
BMD Bending moment theory
AI Artificial intelligence
ML Machine Learning

The study is divided into three stages that are -

- Fabrication of the testing setup
 - Sensor interfacing
 - AI coding and its training.

III. TESTING SETUP DESIGN -

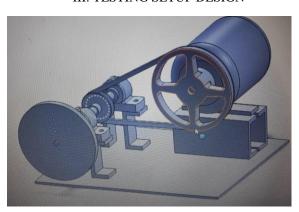


Fig1. Source of vibrations

Equations:

The transmission ratio is the ratio of input speed to the output speed. In order step up the speed on the shaft side inverse transmission ratio is used. The input speed (N_1) is 1440 rpm.

$$i = \frac{D_1}{D_2} = \frac{N_2}{N_1}$$
$$= \frac{203.3}{76.2}$$
$$= 2.667$$

For the speed of shaft

$$2.667 = \frac{N_2}{1440}$$

$$N_2 = 3842 \ rpm$$

The pulleys are selected according to the standard A-section V- belt pulleys on the basis of the transmission ratio and speeds [6]. Motor of 0.5 hp is used in the setup.

Diameter of Shaft

According to the theory of SFD and BMD [8], the bending moment at point C is maximum which is **3090** N-mm and the torsional moment is given by-

$$M_t = (T_1 - T_2)^{\frac{R_1}{2}}$$

$$M_E = \sqrt{M_b^2 + M_t^2}$$

$$= \sqrt{3090.9^2 + 2473.14^2}$$

$$= 3958.55 \text{ N-mm}$$

$$d^{3} = \left(\frac{16}{\pi \times \tau} \sqrt{(M_{t}^{2} + M_{b}^{2})}\right)$$
$$= \frac{16}{\pi \times \tau} \times 3958.55$$

= 7.6508 mm

Nomenclature

 N_1 - input speed

N₂ - output speed

 D_1 - diameter of larger pulley

 D_2 - diameter of smaller pulley

- transmission ratio

 M_t - torsional moment

 M_b - bending moment

diameter of shaft

shear stress τ

horsepower

The minimum value of the diameter of shaft has to be 8mm thus shaft is manufactured with a diameter of 20mm.

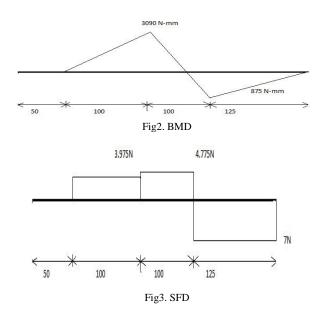


Table 1 Electrical Components

Sr No.	Components	Description
1	Tri-Axial accelerometer	MEMS Vibration Sensor
2.	RS485 to USB Convertor	Serial data transreceiver
3.	Ethernet Shield	Wireless data transmission
4.	Motor	0.5 hp, single phase, 1440 rpm

Frequency Range	400 Hz
Voltage Analogue	0.5 V / 0.10 V (programmable)
Output	
Current Analogue	4-20 mA / 0.20 mA / 0.24 mA (programmable)
Output	
Load Resistance	1k-1M Ohm
(voltage)	
Load Resistance	100-500 Ohm
(current)	
Humidity	< 80 % without condensation

IV. VIBRATION SENSOR -

Sensor interfacing with RS-485 to USB converter and controller is depicted in figure 4.

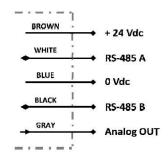


Fig4. Electrical Diagrams of the connections

Principle & Working

Sensor used in this study works on a principle of piezoelectric effect. The effect is a direct conversion of mechanical energy into electrical energy in a crystalline material composed of electric dipoles. It has a natural application in sensing vibration and acceleration. Acceleration of the case moves it relative to mass, which exerts a force on the crystal. The output is directly proportional to the acceleration or vibration level [4].

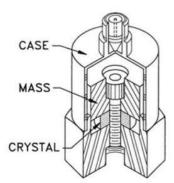


Fig5. Schematic Diagram

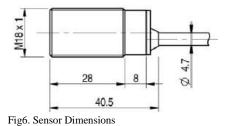


Table 2
Technical Data

Supply Voltage	24 Vdc +/- 20%
Consumption	< 1 W
Operative Range	+/- 16 g (<i>MAX</i>)
Resolution	15,62 mg @ +/- 2 g 31,25 mg @ +/- 4 g 62,50 mg @ +/- 8 g 125 mg @ +/- 16 g

Table 3
Mechanical Components

Sr No.	Components	Description
1.	Bearings	φ 20 mm, seal master type,
2.	Pulley	Aluminium alloy, φ 8 inches and φ 3 inches
3.	MS Base Plate	Mild steel
4.	Shaft	EN8 φ 20 mm and 395 mm length
5.	Channel	Mild steel C-type
6.	Rubber Pad	Hard Rubber
7.	Disc	Cast iron, φ 8 inches

V. ARTIFICIAL INTELLIGENCE

Predictive maintenance is the monitoring of system's condition over its life cycle to provide a prognosis to when maintenance is required. The Predictive maintenance tools are increasingly dependent on machine learning (ML) based artificial intelligence (AI) technology [9]. Currently, there is no architecture or framework that provides a standard of practice for how data should be structured per method of Predictive Maintenance analysis dependent on ML [10]. Thus, data-driven predictive maintenance algorithms could be limited in the ability to provide accurate and current information depending on choice in ML-based analysis [11].

Naïve Bayes Algorithm Naïve Bayes classifier works on probabilistic approach and is a common method for classification. We will be using Naïve Bayes as it is easy to implement and also gives high efficiency as compared to other AI algorithms [12]. The Naive Bayes method is a classification method based on Bayes' Theorem and the conditional independence assumption [13]. For a given training set, $T = \{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}.$

Naïve Bayes first learns the joint probability distribution (x,y) of the input and output by the conditional probability distribution conditional independence assumption. The output label with the biggest posterior implementing Artificial intelligence for predicting the probability for the given input can be calculated [14]. abnormal vibration source [5]. Bayes theorem says that,

 $p(c_j/d) = p(d/c_j) * p(c_j)/p(d)$

 $p(c_i/d)$ is probability of instance d being in class c_i .

 $p(d/c_i)$ is probability of generating instance d given class c_i .

 $p(c_i)$ is probability of occurrence of class c_i .

p(d) is probability of instance d occurring.

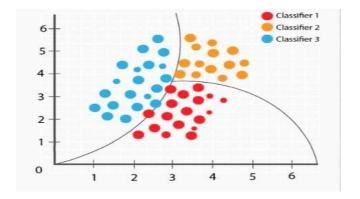


Fig7. Naïve Bayes classifier

Multinomial Naïve Bayes

As we have multiple variants i.e in case of our project different frequency and amplitude combination, we will be using multinomial Naïve Bayes [15]. It estimates the conditional probability of a particular instance given in a class as the relative frequency of term belonging to class. The variation takes into account the number of occurrences of term in training from class, including the multiple occurrences.

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VI. RESULT

In this study, the sources of vibration considered are mass unbalance, misalignment of shaft and fault in bearings. The amplitude of the frequency of these vibration sources along with the ideal conditions are recorded and stored in CSV file (dataset) to analyze the defect in the rotating machine. Excessive vibrations are purposely added in the machine while it is in operating state. Then the AI code predicts the source of abnormal vibration by comparing with the ideal values stored in the CSV file. Abnormal vibration source in the testing setup while in operation, is predicted using Artificial Intelligence.

VII. FUTURE SCOPE

Accessing the machineries remotely via GNU radio in real time is the future work that can be achieved after

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