# Application of Differential Equations 

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#### Abstract

In this paper we show that a method of embedding for a class of non-linear Volterra equations can be used in a novel fashion to obtain variation of parameters formulas for Volterra integral equations subjected to a general type of variation of the equation. The approach is of intrinsic interest. Our variation of parameters formulas generalize classical formulas for ordinary differential equations and for linear Volterra integral equations (based on resolvents). Illustrative examples are related to known results.


Keywords: Volterra equation, integral equation, variation of parameters, ordinary differential equations, linear equations, non linear equations.

## INTRODUTION

Sir Isaac Newton (1642-1727) English scientist and mathematician famous for his discovary of the law of gravity and three laws of motion. Today these laws are known as Newton's laws of motion and descripe the motion of all objects on the scale we experience in our everyday lives. Solved his first differential equation, by the use of infinite series, eleven years after his discovery of calculus in 1665. Gottfried Wilhelm Leibniz (also known as von Leibniz) was a prominent German mathematician, philosopher, physicist and statesman. Noted for his independent invention of the differential and integral calculus, Gottfried Leibniz remains one of the greatest and most influential metaphysicians, thinkers and logicians in history. He also invented the Leibniz wheel and suggested important theories about force, energy and time.

## DEFINITIONS

## Differential equation:

Any relation involving the dependent variable, independent variable (or variables) and the differential coefficient (or coefficients) of the dependent variable with respect to the independent variable(or variables) is known as a differential equation. (Or)

A differential equation is a relationship between a function of time and its derivative.
For example:
$1 \cdot \frac{d y}{d x}=\cot x$
$5 \cdot \frac{d^{2} y}{d x^{2}}+4 y=\tan 2 x$
2. $\frac{d^{2} y}{d x^{2}}+y=0$
6. $x \frac{\partial z}{\partial x}+y \frac{\partial z}{\partial y}=z$
3. $y=x \frac{d y}{d x}+\left(\frac{d y}{d x}\right)^{3}$
7. $\frac{\partial^{2} z}{\partial x \partial y}=\frac{\partial z}{\partial x}$
$4 \cdot \frac{d^{2} y}{d x^{2}}+\sqrt{1+\left(\frac{d y}{d x}\right)^{3}}=0$

$$
\text { 8. } \rho=\frac{\left\{1+\left(\frac{d y}{d x}\right)^{2}\right\}^{3 / 2}}{\frac{d^{2} y}{d x^{2}}}
$$

Are all differential equations.

## VARIATION OF PARAMETER

Variation of parameter is another method for finding a particular solution of the nth-order linear differential equation

$$
L(y)=\varphi(x) \quad-------\rightarrow(1)
$$

Once the solution of the associated homogeneous equation
$L(y)=0$ is known. If $y_{1}(x), y_{2}(x), \cdots, y_{n}(x)$ are n linearly independent solutions of $L(y)=0$, then the general solution of $L(y)=0$ is

$$
y_{h}=c_{1} y_{1}(x)+c_{2} y_{2}(x)+\cdots c_{n} y_{n}(x)---\rightarrow \text { (2) }
$$

The method:
A particular solution of $L(y)=\varphi(x)$ has the form

$$
y_{p}=v_{1} y_{1}+v_{2} y_{2}+\cdots v_{n} y_{n}
$$

Where $y_{i}=y_{i}(x)(i=1,2,3, \cdots, n)$ is given in (2) and $v_{i}(i=1,2, \cdots, n)$ is an unknown function of x which still must be determined.

To find $v_{i}$, first solve the following linear equations simultaneously for $v^{\prime}{ }_{i}$.

$$
\begin{aligned}
& v_{1}^{\prime} y_{1}+v^{\prime}{ }_{2} y_{2}+\cdots+v^{\prime} y_{n}=0 \\
& v_{1}^{\prime} y_{1}^{\prime}{ }_{1}+v^{\prime}{ }_{2} y^{\prime}{ }_{2}+\cdots+v^{\prime}{ }_{n} y^{\prime}{ }_{n}=0 \\
& \vdots \\
& v^{\prime} y_{1}^{(n-2)}+v^{\prime}{ }_{2} y_{2}^{(n-2)}+\cdots+v^{\prime} y_{n}^{(n-2)}=0 \\
& v^{\prime}{ }_{1} y_{1}^{(n-1)}+v^{\prime}{ }_{2} y_{2}^{(n-1)}+\cdots+v^{\prime}{ }_{n} y_{n}^{(n-1)}=\varphi(x)
\end{aligned}
$$

Then integrate each $v_{i}^{\prime}$ to obtain $v_{i}$, disregarding all constraints of integration. This is permissible because we are seeking only one particular solution.

Example :
For the special case $n=3$, reduce to

$$
\begin{gathered}
v_{1}^{\prime} y_{1}+v^{\prime}{ }_{2} y_{2}+v^{\prime}{ }_{3} y_{3}=0 \\
v^{\prime}{ }_{1} y_{1}^{\prime}+v^{\prime}{ }_{2} y^{\prime}{ }_{2}+v^{\prime}{ }_{3} y^{\prime}{ }_{3}=0 \\
v_{1}^{\prime} y^{\prime \prime}{ }_{1}+v^{\prime}{ }_{2} y^{\prime \prime}{ }_{2}+v^{\prime}{ }_{3} y^{\prime \prime}{ }_{3}=\varphi(x)
\end{gathered}
$$

## Problems

1. solve $y^{\prime \prime}+y=\sec x$.

Solution:

$$
\text { Given } y^{\prime \prime}+y=\sec x
$$

This is a third-order equation with

$$
y_{h}=c_{1} \cos x+c_{2} \sin x \quad-----\rightarrow(1)
$$

It follows from equation,

$$
y_{p}=v_{1} \cos x+v_{2} \sin x \quad------\rightarrow(2)
$$

Using linear equation,

$$
\begin{aligned}
v_{1}^{\prime} y_{1}+v_{2}^{\prime} y_{2} & =0 \\
v_{1}^{\prime} y_{1}^{\prime}{ }_{1}+v_{2}^{\prime} y_{2}^{\prime}{ }_{2} & =\varphi(x)
\end{aligned}
$$

Here $y_{1}=\cos x, y_{2}=\sin x \quad \& \quad \varphi(x)=\sec x$

$$
\therefore v_{1}^{\prime} \cos x+v^{\prime}{ }_{2} \sin x=0
$$

$$
\Rightarrow \quad v_{1}^{\prime} \cos x=-v_{2}^{\prime} \sin x
$$

$$
v_{1}^{\prime}=-v^{\prime}{ }_{2} \tan x \rightarrow--(3)
$$

$$
v^{\prime}{ }_{1}(-\sin x)+v_{2}^{\prime} \cos x=\sec x
$$

$\Rightarrow \quad v^{\prime}{ }_{2}(\tan x \sin x)+v^{\prime}{ }_{2} \cos x=\sec x$
$\Rightarrow \quad v^{\prime}\left[\frac{\sin ^{2} x+\cos ^{2} x}{\cos x}\right]=\sec x$

$$
{v^{\prime}}_{2}=\frac{1}{\cos x} \times \cos x=1
$$

$$
\therefore \quad v^{\prime}{ }_{2}=1
$$

$$
(3) \Rightarrow \quad v_{1}^{\prime}=-\tan x
$$

Thus

$$
v_{1}=\int v_{1}^{\prime} d x=\int(-\tan x) d x=\log (\cos x)
$$

$$
v_{2}=\int v^{\prime}{ }_{2} d x=\int d x=x
$$

$$
\therefore \quad v_{1}=\log (\cos \mathrm{x}) \quad \& \quad \mathrm{v}_{2}=\mathrm{x}
$$

Substituting these values into (2) we obtain

$$
y_{p}=\log (\cos x) \cos x+x \sin x
$$

The general solution is

$$
\begin{aligned}
y & =y_{h}+y_{p} \\
& =c_{1} \cos x+c_{2} \sin x+\cos x(\log (\cos x))+x \sin x
\end{aligned}
$$

2. solve $y^{\prime \prime}-y^{\prime}-2 y=e^{3 x}$

Solution:
This is second-order equation
Here $\mathrm{n}=2$ \& $y_{h}=c_{1} e^{-x}+c_{2} e^{2 x}$
Hence $\quad y_{p}=v_{1} e^{-x}+v_{2} e^{2 x}$
Using linear equation is

$$
\begin{align*}
& v_{1}^{\prime} y_{1}+v_{2}^{\prime} y_{2}=0  \tag{1}\\
& v^{\prime}{ }_{1} y^{\prime}{ }_{1}+v^{\prime}{ }_{2} y^{\prime}{ }_{2}=\varphi(x) \\
& \text { here } y_{1}=e^{-x}, y_{2}=e^{2 x} \quad \& \quad \varphi(x)=e^{3 x}, \\
& \therefore v^{\prime}{ }_{1} e^{-x}+v^{\prime}{ }_{2} e^{2 x}=0  \tag{2}\\
& \Rightarrow \\
& v_{1}^{\prime} e^{-x}=-v^{\prime}{ }_{2} e^{2 x} \\
& v_{1}^{\prime}=-v_{2}^{\prime} e^{3 x} \\
& \&-v^{\prime}{ }_{1}\left(-e^{-x}\right)+2 v^{\prime}{ }_{2} e^{2 x}=0 \\
& \Rightarrow \\
& v^{\prime}{ }_{2} e^{2 x}+2 v^{\prime}{ }_{2} e^{2 x}=e^{3 x} \\
& 3 v^{\prime}{ }_{2} e^{2 x}=e^{3 x} \\
& v_{2}^{\prime}=\frac{e^{x}}{3} \\
& \text { (2) } \Rightarrow \\
& v_{1}^{\prime} e^{-x}=-\frac{e^{3 x}}{3} \\
& v_{1}^{\prime}=-\frac{e^{4 x}}{3} \\
& \therefore \quad v_{1}^{\prime}=-\frac{e^{4 x}}{3} \quad \& \quad v_{2}^{\prime}=\frac{e^{x}}{3} \\
& \text { Thus } \\
& v_{1}=\int v_{1}^{\prime} d x=\int-\frac{e^{4 x}}{3} d x \\
& =-\frac{1}{3} \frac{e^{4 x}}{4}=-\frac{e^{4 x}}{12} \\
& v_{2}=\int v^{\prime}{ }_{2} d x=\int \frac{e^{x}}{3} d x \\
& v_{2}=\frac{e^{x}}{3} \\
& \therefore \quad v_{1}=-\frac{e^{4 x}}{12} \quad \& \quad v_{2}=\frac{e^{x}}{3}
\end{align*}
$$

Substituting these values into (1) we obtain

$$
\begin{aligned}
y_{p} & =-\frac{e^{4 x}}{12} e^{-x}+\frac{e^{x}}{3} e^{2 x} \\
& =-\frac{e^{3 x}}{12}+\frac{e^{3 x}}{3}=\frac{-e^{3 x}+4 e^{3 x}}{12} \\
y_{p} & =\frac{e^{3 x}}{4}
\end{aligned}
$$

The general solution is,

$$
y=y_{h}+y_{p}=c_{1} e^{-x}+c_{2} e^{2 x}+\frac{e^{3 x}}{4}
$$

## CONCLUSION

I am very glad that I had an opportunity to do an independent paper in differential equation \& their application. In the short span of time I have done best of my level. I scincerely hope that this small paper work will inspire the reader to do further reading in this field. This paper is mainly concerned with many interesting chapters such as basic concepts of differential equation, variation of parameter \& etc.

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