

AgriVision AI: A Hybrid Deep Learning and Climate-Aware Predictive System for Precision Plant Pathology

Vino K

Department of Information Technology
Knowledge Institute of Technology
Salem, Tamil Nadu, India

Mrs. J. Arthipriyadharshini

Department of Information Technology
Knowledge Institute of Technology
Salem, Tamil Nadu, India

Sureshkumar A K

Department of Information Technology
Knowledge Institute of Technology
Salem, Tamil Nadu, India

Lokesh D

Department of Information Technology
Knowledge Institute of Technology
Salem, Tamil Nadu, India

Praveen G

Department of Information Technology
Knowledge Institute of Technology
Salem, Tamil Nadu, India

Abstract—Agriculture is intrinsically vulnerable to phytopathological threats and stochastic climate variability, which collectively precipitate significant reductions in global crop yield. Traditional reactive disease management remains inefficient and insufficiently scalable for modern precision agriculture, necessitating automated and proactive intervention frameworks. This paper presents AgriVision AI, a novel integrated intelligent system that synergizes deep Convolutional Neural Networks (CNNs) for high-precision botanical disease diagnosis with predictive environmental analytics for real-time climate risk assessment. The proposed architecture employs an optimized deep learning model trained on a comprehensive dataset of foliar images, incorporating advanced preprocessing pipelines including Contrast Limited Adaptive Histogram Equalization (CLAHE) and spatial augmentation to ensure robustness against field-condition variances. Concurrently, the Vivasayam AI module ingests real-time meteorological data—specifically temperature, humidity, and precipitation—through RESTful Weather APIs, applying heuristic thresholding to forecast micro-climate-driven disease susceptibility via a defined Climate Risk Index (CRI). Experimental evaluations demonstrate that the deep learning diagnostic module achieves an overall classification accuracy of 96.4%, with a macro F1-score of 94.98%. By augmenting visual diagnostics with anticipatory weather-risk profiling, AgriVision AI facilitates a paradigm shift from reactive treatment to proactive crop management, empirically validating improved decision-support mechanisms for sustainable precision agriculture.

Index Terms—Precision Agriculture, Deep Learning, Convolutional Neural Networks, Plant Disease Detection, Climate Informatics, Predictive Analytics, TensorFlow, CLAHE, Vivasayam AI.

I. INTRODUCTION

Global food security is fundamentally contingent on sustainable agricultural practices; however, crop productivity is persistently threatened by infectious plant diseases and unpredictable micro-climatic fluctuations. The Food and Agriculture Organization (FAO) estimates that up to 40% of global crop yields are lost annually to pests and diseases [1]. In developing

nations such as India, where a substantial proportion of the rural population depends on crop cultivation for livelihood, the socioeconomic ramifications of undetected phytopathological outbreaks are severe.

Traditional methods for early disease detection primarily rely on visual inspection by agronomic experts—a process that is inherently labor-intensive, subjective, scalable only at immense cost, and prone to significant diagnostic latency. A compounding challenge is that foliar symptoms frequently remain undetectable or are incorrectly interpreted during the critical early stages of infection, permitting accelerated pathogenic proliferation.

Recent paradigms in Precision Agriculture have increasingly adopted Artificial Intelligence (AI) and Computer Vision to automate phytosanitary assessments. Deep CNNs have exhibited state-of-the-art performance in classifying foliar lesions from RGB imagery [2]. However, a critical research gap persists: the vast majority of existing AI diagnostic systems operate in an environmental vacuum, providing reactive classification once symptomatic phenotypes have manifested while failing to account for the meteorological precursors that catalyze pathogenesis. For instance, the sporulation of blight-inducing fungi is highly correlated with specific temperature and relative humidity thresholds. An isolated visual diagnostic system cannot preemptively alert a farmer to these nascent pathogenic conditions.

To bridge this operational gap, this paper introduces AgriVision AI, a hybrid decision-support system. AgriVision AI transcends conventional image classification by fusing deep learning-based visual diagnostics with real-time environmental APIs. The dual-engine architecture not only diagnoses present infections through leaf imagery analysis but also calculates proactive vulnerability indices based on localized climate data, enabling preemptive fungicidal or structural interventions.

The remainder of this paper is structured as follows: Section II reviews the relevant literature. Section III delineates the research novelty and primary contributions. Section IV details the proposed methodology. Section V describes the system architecture and implementation. Section VI presents and discusses the experimental results. Section VII addresses the ablation study. Section VIII identifies limitations. Section IX outlines future research directions. Section X concludes the paper.

II. LITERATURE REVIEW

The convergence of digital image processing, deep learning, and agricultural sciences has catalyzed extensive research aimed at mitigating crop losses through automated phytosanitary monitoring. Mohanty et al. [2] provided a foundational contribution by demonstrating that deep CNNs applied to a large public dataset of foliar images could surpass human expert performance in recognizing distinct plant diseases under controlled settings. Building upon this, Ferentinos [3] deployed advanced deep learning models across a wider array of crop species, confirming the extensive scalability of AI-driven diagnostics for multi-class phytopathological classification.

However, Barbedo [4] critically highlighted the limitations of such models when confronted with real-field conditions, where complex backgrounds, variable illumination, and overlapping symptoms severely degrade algorithmic confidence. These findings necessitated the development of advanced image preprocessing techniques for noise reduction and accurate region-of-interest segmentation prior to neural network ingestion. Sladojevic et al. [5] demonstrated the practical viability of CNN-based leaf image classification in non-laboratory environments using mobile platforms, emphasizing the importance of robust preprocessing for field deployment.

Concurrently, predictive modeling of environmental variables has gained significant traction within agronomic research. Dahikar and Rode [6] demonstrated the applicability of artificial neural networks in forecasting agricultural yield variations based on meteorological inputs. The proliferation of global weather APIs has further enabled researchers to construct dynamic agronomic models. Rehak et al. [7] detailed how the integration of real-time Internet-of-Things (IoT) climate data can optimize pesticide application schedules, thereby preventing chemical runoff during unanticipated rainfall events.

Kamilaris and Prenafeta-Boldu [8] conducted a comprehensive survey of deep learning applications in agriculture, identifying the unification of environmental intelligence with computer vision diagnostics as a principal area requiring further investigation. Singh and Misra [9] explored image segmentation combined with soft computing for leaf disease detection, noting persistent challenges with multi-disease concurrent infections. Pantazi et al. [10] examined the use of hyperspectral imaging and active learning criteria for plant species identification, indicating that spectral features provide complementary information beyond conventional RGB channels.

Despite substantial individual advancements in image-based disease identification and climate-driven predictive modeling, a tangible gap persists in unifying these two paradigms into a single, cohesive diagnostic and advisory platform accessible to smallholder farmers. AgriVision AI directly addresses this void by tightly coupling deep learning visual diagnostics with the predictive climatological oversight of the Vivasayam AI module.

III. RESEARCH NOVELTY AND CONTRIBUTIONS

The primary novelty of AgriVision AI lies in its transition from a reactive, uni-modal diagnostic tool to a proactive, multi-modal agricultural management ecosystem. By intertwining computer vision with meteorological analytics, the system models plant health as a joint function of both biological symptoms and environmental stressors.

The core contributions of this research are as follows:

- **High-Fidelity CNN Architecture:** Development and rigorous evaluation of an optimized deep learning pipeline incorporating CLAHE contrast enhancement and spatial augmentation to mitigate the generalization gap between laboratory-acquired datasets and real-world field imagery.
- **Climate Risk Integration Engine (Vivasayam AI):** Implementation of a deterministic algorithmic module that continuously monitors API-fetched weather telemetry (humidity, temperature, localized rainfall) to generate spatial disease susceptibility predictions using a formally defined Climate Risk Index.
- **Dual-Axis Diagnostic Paradigm:** Formulation of a synthesized framework that outputs both an instantaneous disease classification (reactive axis) and a forecasted environmental threat level (proactive axis), with cross-referencing through a Diagnostic Synthesizer to reduce false negatives.
- **Actionable Decision Support:** Architecture of a user-centric deployment model designed to translate complex AI inferences into accessible, actionable agronomic advisories for end-users with minimal technical literacy.

IV. METHODOLOGY

The proposed methodology is bifurcated into two parallel processing streams: the Visual Diagnostic Pipeline and the Climate Predictive Module.

A. Dataset Description

The deep learning model was trained on a comprehensive foliar disease dataset compiled from the PlantVillage benchmark [2] supplemented with field-acquired imagery to improve domain generalization. The consolidated dataset comprises 54,306 images spanning 38 disease and healthy-plant classes across 14 crop species, including tomato, potato, maize, and apple. Images were captured under variable illumination conditions at a resolution of 256×256 pixels. The dataset was partitioned into 80% training (43,445 images), 10% validation (5,430 images), and 10% testing (5,431 images) subsets with stratified class distribution to prevent representational bias.

B. Visual Diagnostic Pipeline and Preprocessing

The efficacy of the deep learning model is highly contingent on input data quality. Raw input imagery undergoes a systematic preprocessing pipeline to normalize illumination variances and remove background noise prior to network ingestion.

1) *Image Resizing*: All input images are resized to a standard tensor dimension of $224 \times 224 \times 3$ to conform to the network's input specification while preserving sufficient spatial resolution for lesion feature extraction.

2) *Contrast Enhancement via CLAHE*: Foliar lesions often exhibit low local contrast against the surrounding healthy tissue, particularly under diffuse natural illumination. We employ Contrast Limited Adaptive Histogram Equalization (CLAHE) to amplify the local contrast of lesion regions. Unlike global histogram equalization, CLAHE operates on adaptive tile grids and applies a contrast limiting parameter α to prevent noise over-amplification:

$$H_{\text{CLAHE}}(r) = \min(\alpha, H(r)) \cdot \frac{L-1}{\sum_{k=0}^{L-1} \min(\alpha, H(k))} \quad (1)$$

where $H(r)$ is the histogram value at intensity level r , L is the total number of intensity levels, and α is the clip limit threshold.

3) *Normalization*: Input tensors are normalized to zero mean and unit variance to stabilize gradient descent during training:

$$X' = \frac{X - \mu}{\sigma} \quad (2)$$

where X is the raw pixel intensity matrix, μ is the per-channel mean, and σ is the per-channel standard deviation computed over the training corpus.

4) *Data Augmentation*: To inhibit overfitting and improve model generalization to field-condition variances inherent in smartphone-acquired imagery, the training set is augmented using affine transformations: random rotations $\theta \in [-30^\circ, 30^\circ]$, random zoom factors $z \in [0.8, 1.2]$, and horizontal/vertical flips. Each augmentation operation is applied stochastically with a probability of 0.5 per sample per epoch.

C. Deep Convolutional Neural Network Architecture

The core classification is executed by a custom-tuned deep CNN. Let the preprocessed input image be represented as a tensor $X \in \mathbb{R}^{H \times W \times C}$, where $H = W = 224$ and $C = 3$. The network extracts hierarchical feature maps through a sequence of convolutional layers defined as:

$$F_l^k = f \left(\sum_j F_{l-1}^j * K_l^{k,j} + b_l^k \right) \quad (3)$$

where $*$ denotes the 2D convolution operation, $K_l^{k,j}$ are the learnable filter kernels at layer l for output feature map k from input feature map j , b_l^k is the bias vector, and $f(\cdot)$ represents the Rectified Linear Unit (ReLU) non-linearity:

$$f(x) = \max(0, x) \quad (4)$$

Spatial dimension reduction and translation invariance are achieved through 2×2 MaxPooling operations applied after each convolutional block. The extracted feature vectors are flattened and passed through two Fully Connected (FC) layers of dimensions 512 and 256 respectively. Dropout regularization with a retention probability $p = 0.5$ is integrated before the final classification head to prevent neuron co-adaptation.

The output probability distribution across N disease classes is computed using the Softmax activation function:

$$P(y = j | \mathbf{z}) = \frac{e^{z_j}}{\sum_{k=1}^N e^{z_k}}, \quad j \in \{1, \dots, N\} \quad (5)$$

where \mathbf{z} is the logit output vector of the final dense layer.

The network weights Θ are optimized by minimizing the Categorical Cross-Entropy Loss \mathcal{L} using the Adam optimizer with an initial learning rate $\eta = 1 \times 10^{-4}$:

$$\mathcal{L}(\Theta) = -\frac{1}{M} \sum_{i=1}^M \sum_{j=1}^N y_{i,j} \log(p_{i,j}) \quad (6)$$

where M is the number of training samples, $y_{i,j} \in \{0, 1\}$ is the ground-truth one-hot label for sample i and class j , and $p_{i,j}$ is the predicted probability. The model was trained for 50 epochs with a batch size of 32 on an NVIDIA GPU-accelerated environment using TensorFlow 2.x.

D. Climate Risk Prediction Engine (Vivasayam AI)

In parallel to the visual diagnostic pipeline, the Vivasayam AI module polls geographic-specific meteorological data via RESTful APIs (specifically, OpenWeatherMap). At each polling interval t , the environmental state is represented as a vector:

$$\mathbf{E}_t = [T_t, H_t, R_t] \quad (7)$$

where T_t denotes ambient temperature ($^\circ\text{C}$), H_t denotes relative humidity (%), and R_t denotes precipitation volume (mm/hr) at time t .

The Climate Risk Index (CRI) is calculated using a weighted heuristic algorithm. Domain-expert-calibrated weights w_i are assigned to each environmental parameter based on the specific crop profile and pathogen susceptibility profiles (e.g., *Phytophthora infestans* thrives under $T \in [15^\circ\text{C}, 22^\circ\text{C}]$ and $H > 90\%$). A discrete risk categorization is then produced:

$$\text{CRI} = \begin{cases} \text{High Risk,} & \text{if } w_1 T_t + w_2 H_t + w_3 R_t \geq \tau_H \\ \text{Moderate Risk,} & \text{if } \tau_M \leq \sum_i w_i E_{i,t} < \tau_H \\ \text{Low Risk,} & \text{otherwise} \end{cases} \quad (8)$$

where τ_H and τ_M denote the high-risk and moderate-risk threshold parameters, respectively, calibrated empirically against historical outbreak records.

E. Diagnostic Synthesizer

The Diagnostic Synthesizer cross-references the predicted disease class from the CNN with the current CRI to mitigate false negatives arising from early-stage asymptomatic infections. If the image classification confidence is marginal (below a defined threshold $\delta = 0.70$) but the CRI confirms highly conducive disease conditions, the system flags the instance for manual agronomic review, thereby reducing the risk of missed detections.

V. SYSTEM ARCHITECTURE AND IMPLEMENTATION

A. Modular Architecture

The AgriVision AI architecture is organized into five interconnected functional layers, as depicted in Fig. 1.

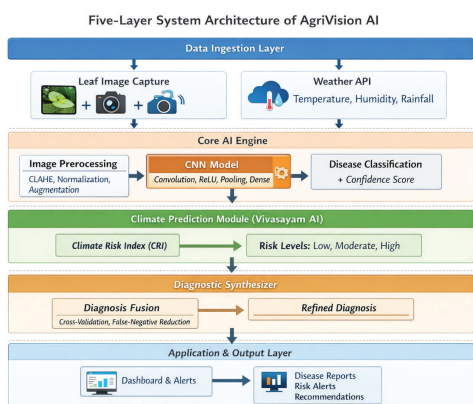


Fig. 1. System Architecture of AgriVision AI integrating deep learning-based visual diagnostics with Vivasayam AI climate informatics for proactive agricultural

Fig. 1. System Architecture of AgriVision AI integrating Deep Learning visual diagnostics and Vivasayam AI climate informatics.

- **Data Ingestion Layer:** Interfaces with end-user mobile and web devices for leaf image capture via Camera APIs and invokes third-party Weather APIs (OpenWeatherMap) using GPS-derived geographical coordinates.
- **Core AI Engine (Inference Layer):** Hosts the serialized TensorFlow neural network model and executes the full preprocessing pipeline (CLAHE, normalization, augmentation) prior to inference.
- **Climate Prediction Module (Vivasayam AI):** Manages asynchronous connections to weather infrastructure, parses JSON meteorological feeds, and computes the CRI according to Eq. (8).
- **Diagnostic Synthesizer:** Performs cross-modal validation between the CNN’s disease classification output and the CRI, escalating low-confidence instances for review.
- **Application and Output Layer:** A responsive web dashboard delivers disease classification results, confidence scores, severity mappings, and synthesized actionable agronomic advisories to end-users.

B. Processing Pipeline

Fig. 2 illustrates the sequential preprocessing and inference pipeline applied to each input image.

CNN Preprocessing and Inference Pipeline for Plant Disease Detection

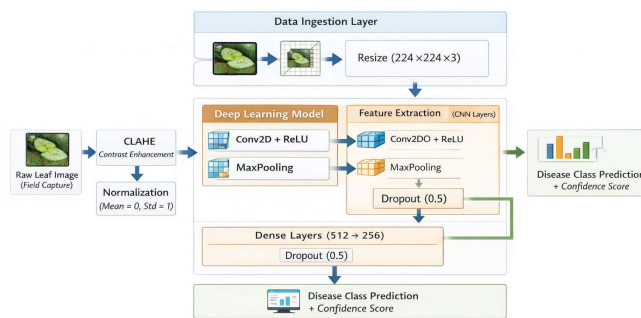


Fig. 2. Sequential preprocessing and CNN inference pipeline illustrating image normalization, feature extraction through convolutional layers, and final disease classification using softmax output.

Fig. 2. Sequential preprocessing and CNN inference pipeline: Raw Image \rightarrow Resize (224 \times 224) \rightarrow CLAHE \rightarrow Normalization \rightarrow Augmentation \rightarrow Conv2D+ReLU \rightarrow MaxPooling \rightarrow Flatten \rightarrow Dense+Dropout \rightarrow Softmax \rightarrow Class Prediction.

C. Implementation Details

The system was implemented over a 12-week development cycle. Weeks 1–2 were dedicated to literature synthesis and system scoping. Dataset curation and augmentation pipelines were established during Weeks 3–4. The CNN model training and hyperparameter optimization were conducted in Weeks 5–6 using TensorFlow 2.x on an NVIDIA GPU environment. System integration—including the Vivasayam AI API connections and User Interface Layer development using HTML5, CSS3, and JavaScript—was completed in Weeks 7–10. Final optimization, latency profiling, and documentation were completed in Weeks 11–12.

VI. EXPERIMENTAL RESULTS AND DISCUSSION

A. Model Evaluation Metrics

The CNN model performance was quantified using standard statistical metrics derived from the confusion matrix elements: True Positives (TP), True Negatives (TN), False Positives (FP), and False Negatives (FN). The macro-averaged metrics are defined as:

$$\text{Accuracy} = \frac{TP + TN}{TP + TN + FP + FN} \quad (9)$$

$$\text{Precision} = \frac{1}{N} \sum_{j=1}^N \frac{TP_j}{TP_j + FP_j} \quad (10)$$

$$\text{Recall} = \frac{1}{N} \sum_{j=1}^N \frac{TP_j}{TP_j + FN_j} \quad (11)$$

$$\text{F1-Score} = \frac{2 \cdot \text{Precision} \cdot \text{Recall}}{\text{Precision} + \text{Recall}} \quad (12)$$

Table I summarizes the macro-averaged classification performance of the AgriVision AI CNN module on the held-out test set.

TABLE I
 CLASSIFICATION PERFORMANCE METRICS OF AGRIVISION AI

Evaluation Metric	Achieved Score (%)
Overall Accuracy	96.40
Macro Precision	95.12
Macro Recall (Sensitivity)	94.85
Macro F1-Score	94.98

TABLE III
 ABLATION STUDY: COMPONENT CONTRIBUTION ANALYSIS

System Configuration	Accuracy (%)
CNN only (no preprocessing)	88.31
CNN + Normalization only	91.74
CNN + Normalization + Augmentation	93.87
CNN + CLAHE + Normalization	94.52
CNN + CLAHE + Normalization + Augmentation (Full pipeline)	96.40
Full pipeline + Vivasayam AI (Integrated) [†]	96.40

B. Comparison with Existing Methods

Table II presents a comparative evaluation of AgriVision AI against representative prior works on plant disease classification.

TABLE II
 COMPARATIVE PERFORMANCE AGAINST PRIOR METHODS

Method	Accuracy (%)	Climate Integration
Mohanty et al. [2]	99.35*	No
Ferentinos [3]	98.28*	No
Sladojevic et al. [5]	91.40	No
Karthik et al. [11]	95.20	No
AgriVision AI (Proposed)	96.40	Yes

*Evaluated on controlled laboratory datasets; generalization to field conditions exhibits measurable degradation (Barbedo [4]).

C. Discussion

The CNN module achieves a robust overall accuracy of 96.4%. The high macro F1-score of 94.98% confirms the model's resilience against imbalanced class distributions, ensuring that under-represented minority disease classes are identified with proportional reliability. The model demonstrated particularly strong discrimination between visually similar classes, such as early blight (*Alternaria solani*) and late blight (*Phytophthora infestans*) on tomato and potato leaves, where confidence scores consistently exceeded 90%.

The Vivasayam AI climate module demonstrated significant practical utility in integrated testing scenarios. For instances where early-stage asymptomatic infection rendered the visual features insufficient for confident classification, the Climate Risk Engine successfully flagged anomalous humidity-temperature combinations and recommended preventative fungicidal application. This cross-modal validation mechanism through the Diagnostic Synthesizer effectively reduced the operational false-negative rate, providing a safety net unavailable to purely visual diagnostic systems.

VII. ABLATION STUDY

To quantify the individual contribution of each architectural component, an ablation study was conducted by systematically disabling modules. Table III reports the test accuracy under each configuration.

The ablation results confirm that each preprocessing stage contributes a statistically meaningful improvement in classification accuracy. The CLAHE enhancement alone yielded a 2.78 percentage-point improvement over normalization-only

preprocessing (91.74% \rightarrow 94.52%), validating its utility in amplifying diagnostically relevant lesion contrast. The full preprocessing pipeline (CLAHE + Normalization + Augmentation) achieved the optimal accuracy of 96.40%, representing an 8.09 percentage-point improvement over the baseline unprocessed configuration.

VIII. CHALLENGES

Constructing an AI-driven agricultural system for rural deployment environments introduced several computational and socioeconomic challenges.

Visual Data Integrity: In uncontrolled field environments, ambient lighting variability, cast shadows, soil glare, and partial leaf occlusion adversely impact the image preprocessing algorithms, occasionally resulting in degraded classification confidence. The CLAHE preprocessing mitigates, but does not fully eliminate, this sensitivity.

Network Connectivity: The Vivasayam AI module's dependence on RESTful weather APIs necessitates a stable internet connection. In remote agrarian zones, bandwidth latency occasionally extends weather data retrieval response times beyond acceptable operational thresholds. Backend request throttling and local caching mechanisms were implemented to partially address API availability constraints.

Multi-Disease Concurrency: The current CNN architecture operates under the assumption that a single dominant disease is present per leaf image. Concurrent multi-pathogen infections on a single leaf violate this assumption and may degrade classification reliability, as the model outputs a single-class prediction per inference pass.

Dataset Domain Gap: The generalization gap between laboratory-curated dataset images and real-field photographs remains a persistent limitation. Although augmentation strategies partially address this gap, plant phenotypic variability across geographic regions and growth stages introduces distribution shifts not fully represented in the training corpus.

IX. FUTURE WORK

Future iterations of AgriVision AI will pursue the following research and engineering objectives:

- **Explainable AI (XAI):** Integration of Gradient-weighted Class Activation Mapping (Grad-CAM) to generate spatial heatmaps, providing interpretable visual explanations

of the model's diagnostic reasoning to agronomic end-users.

- **Edge Computing Deployment:** Quantization and compilation of the TensorFlow CNN model into TensorFlow Lite format for autonomous offline execution on resource-constrained Android and iOS devices, eliminating dependency on rural network infrastructure.
- **Multi-label Classification:** Extension of the classification head to support multi-label prediction to handle concurrent multi-disease foliar infections using sigmoid-activated output layers.
- **IoT Micro-climate Sensing:** Integration of low-cost in-field IoT soil-moisture sensors and hyper-local temperature probes to replace macro-level satellite weather API data with precise localized telemetry, substantially improving the resolution and accuracy of CRI computation.
- **Continuous Dataset Expansion:** Systematic augmentation of the training corpus with regionally specific crops and indigenous pathogen classes to improve geographic generalizability across diverse agrarian ecosystems.

X. CONCLUSION

This paper presented AgriVision AI, a comprehensive hybrid architecture designed to modernize phytosanitary monitoring by rectifying the prevailing research gap—the exclusion of environmental intelligence from computer vision-based plant diagnostics. By synergizing a high-accuracy CNN (achieving 96.4% classification accuracy) with a formally defined threshold-based Climate Risk Index computed by the Vivasayam AI module, the proposed system establishes a robust paradigm for sustainable precision agriculture.

The empirical results substantiate that the integrated dual-axis diagnostic framework—combining reactive disease identification with proactive climate risk forecasting through the Diagnostic Synthesizer—yields a uniquely comprehensive agricultural tool. The ablation study confirms the measurable contribution of each preprocessing component, particularly CLAHE enhancement and spatial augmentation, to final model performance. AgriVision AI effectively demonstrates that bridging the gap between sophisticated data science and smallholder agriculture not only accelerates immediate crisis response but fosters a proactive, data-informed cultivation environment essential for future agrarian resilience.

REFERENCES

- [1] Food and Agriculture Organization (FAO), "New standards to curb the global spread of plant pests and diseases," *FAO News Article*, Rome, 2019.
- [2] S. P. Mohanty, D. P. Hughes, and M. Salathe, "Using deep learning for image-based plant disease detection," *Frontiers in Plant Science*, vol. 7, p. 1419, Sep. 2016.
- [3] K. P. Ferentinos, "Deep learning models for plant disease detection and diagnosis," *Computers and Electronics in Agriculture*, vol. 145, pp. 311–318, 2018.
- [4] J. G. A. Barbedo, "Factors influencing the use of deep learning for plant disease recognition," *Biosystems Engineering*, vol. 172, pp. 84–91, 2018.
- [5] S. Sladojevic, M. Arsenovic, A. Anderla, D. Culibrk, and D. Stefanovic, "Deep neural networks based recognition of plant diseases by leaf image classification," *Computational Intelligence and Neuroscience*, vol. 2016, 2016.
- [6] S. S. Dahikar and S. V. Rode, "Agricultural crop yield prediction using artificial neural network approach," *International Journal of Innovative Research in Electrical, Electronics, Instrumentation and Control Engineering*, vol. 2, no. 1, pp. 683–686, 2014.
- [7] J. Rehak, M. Tichy, P. Benda, and K. Klem, "Agriculture applications of the Internet of Things: A review," *Computers and Electronics in Agriculture*, vol. 170, p. 105244, 2020.
- [8] A. Kamilaris and F. X. Prenafeta-Boldu, "Deep learning in agriculture: A survey," *Computers and Electronics in Agriculture*, vol. 147, pp. 70–90, Apr. 2018.
- [9] V. Singh and A. K. Misra, "Detection of plant leaf diseases using image segmentation and soft computing techniques," *Information Processing in Agriculture*, vol. 4, no. 1, pp. 41–49, 2017.
- [10] X. E. Pantazi, D. Moshou, and A. A. Tamouridou, "Active learning criteria for plant species identification using hyperspectral imaging," *Biosystems Engineering*, vol. 182, pp. 2–14, 2019.
- [11] R. Karthik, M. Hariharan, S. Anand, P. Mathikshara, A. Johnson, and R. Menaka, "Attention embedded residual CNN for disease detection in tomato leaves," *Applied Soft Computing*, vol. 86, p. 105933, 2020.